

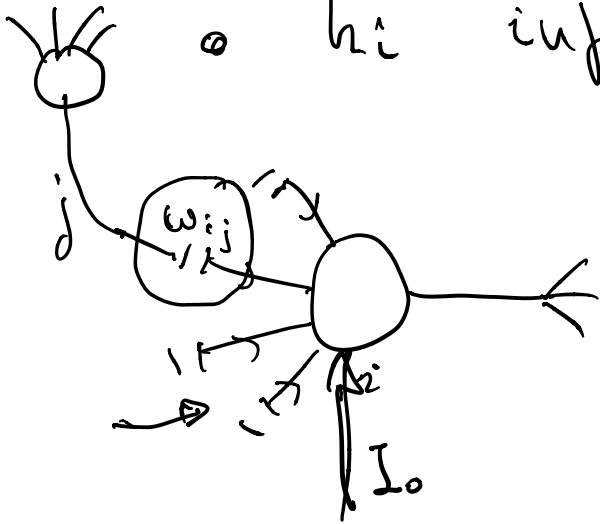
Neurona Artificial

McCulloch and Pitts 1943

- u_i describe la neurona i
- y_i modela la salida (output)

- h_i input

$$h_i(t) = \sum_{j=1}^N w_{ij} y_j(t)$$



- puede haber un término externo
la neurona tiene un estímulo
 $h_i(t) + I_0$

- tiene un umbral de activación
 μ_i

• Función de activación

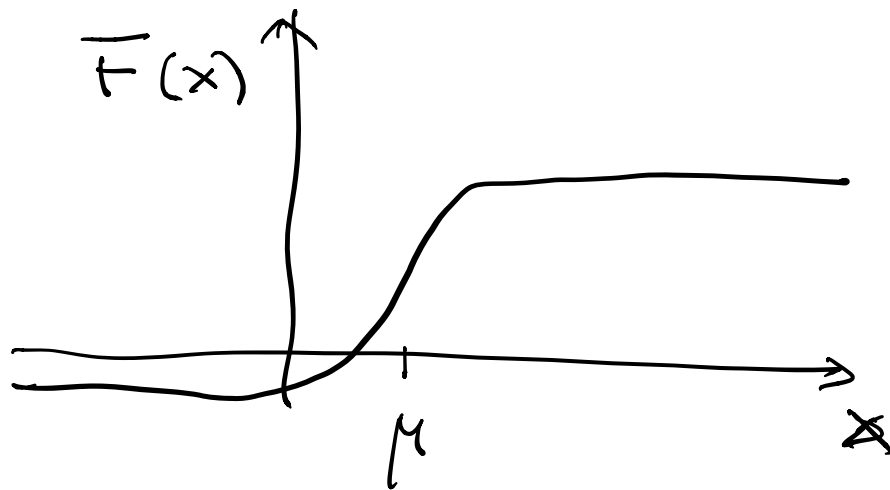
$$y_i(t + \Delta t) = F(h_i(t) + I_0 - \mu_i)$$

Sometimes $I_0 = 0$

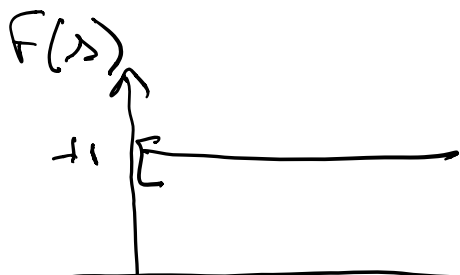
$$y_i(t + \Delta t) = F(h_i(t) - \mu_i)$$

$$\bar{F} : h_i \rightarrow y_i$$

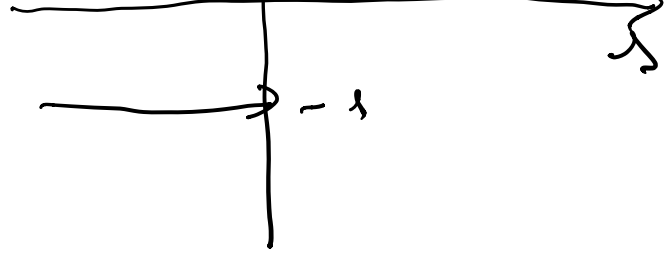
Típicamente



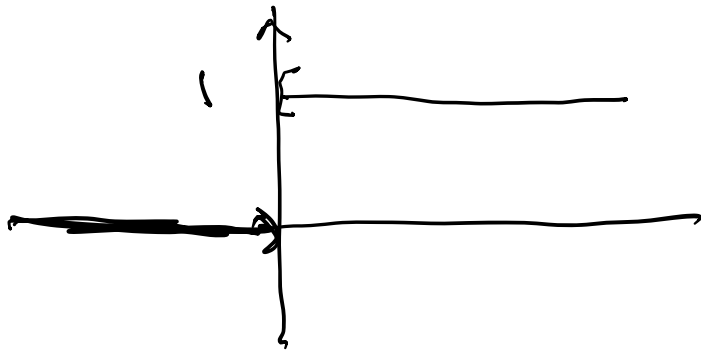
Ejemplos



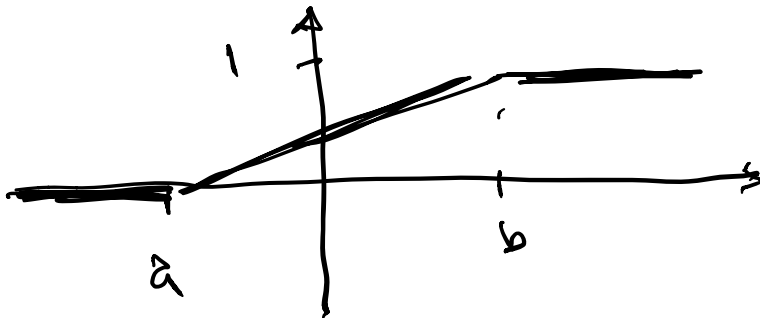
$$F(x) = \text{sign}(x) = \begin{cases} +1 & x \geq 0 \\ -1 & x < 0 \end{cases}$$



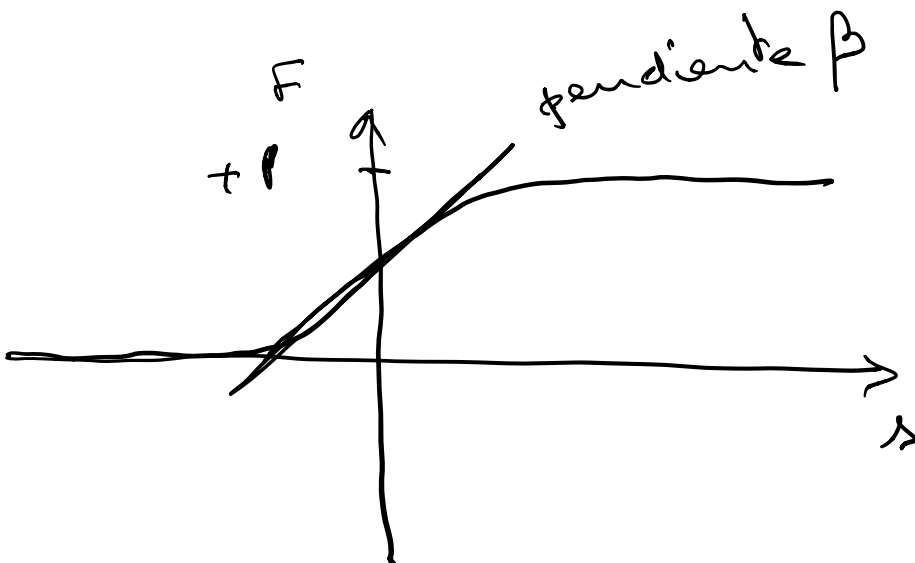
$$F(s) = \begin{cases} 1 & s \geq 0 \\ 0 & s < 0 \end{cases}$$



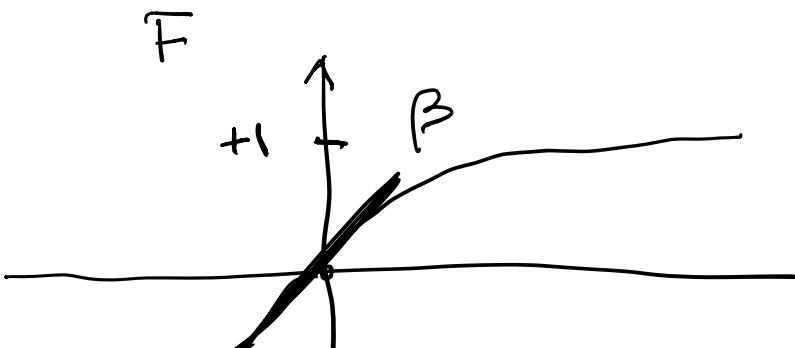
$$F(s) = H(s) = \begin{cases} 1 & s \geq 0 \\ 0 & s < 0 \end{cases}$$



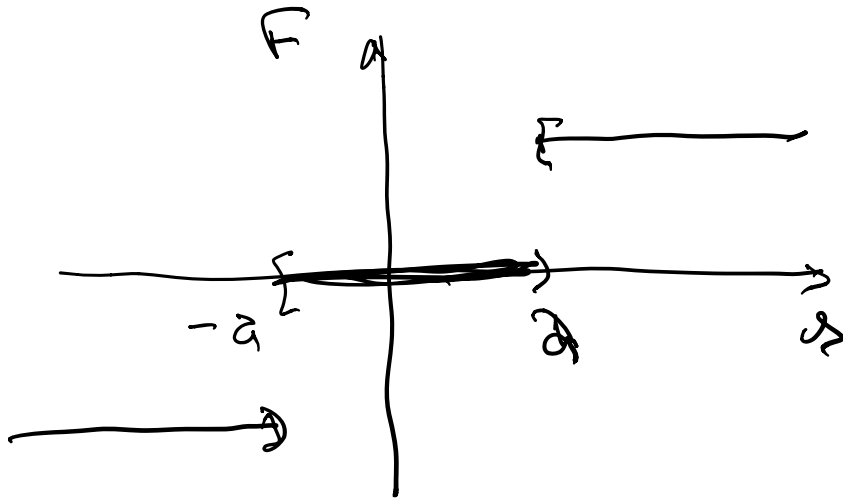
$$F(s) = \begin{cases} 0 & s < a \\ \text{rect} & a < s < b \\ 1 & s > b \end{cases}$$



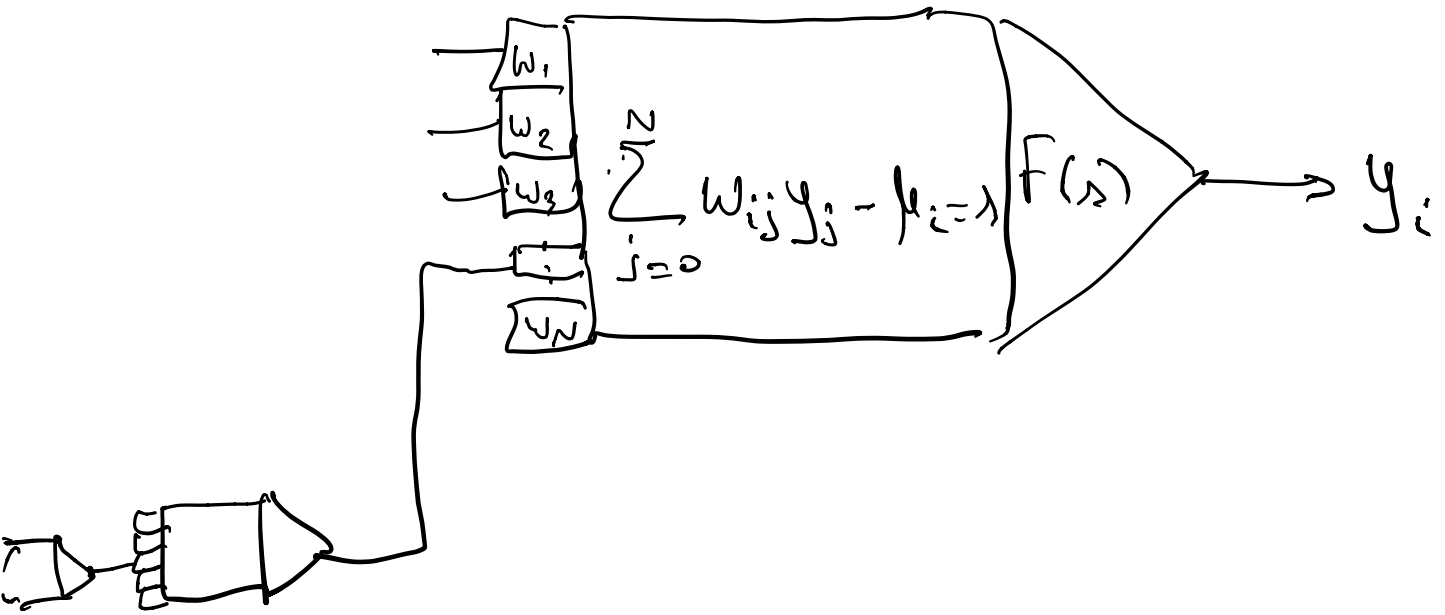
$$F(s) = \frac{p}{1 + e^{-\beta s}}$$



$$F(s) = \tanh(\beta s)$$



$$F_{\lambda}(s) = \begin{cases} +1 & s > a \\ 0 & -a < s < a \\ -1 & s < -a \end{cases}$$



los sinapsis son no reales

$w_{ij} < 0$ sinapsis inhibitoria

$w_{ij} > 0$ " excitatoria

$w_{ij} = 0$ " inerte

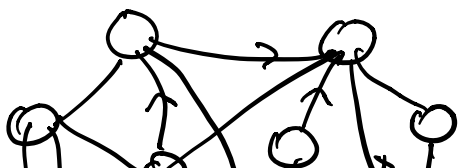
$|w_{ij}|$ es una medida de la fuerza

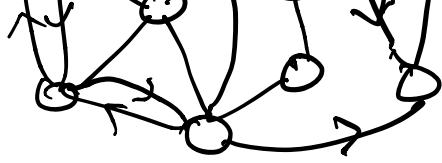
w_{ij} sinopsis entre j e i
↑
pre

El tiempo es discreto, la red se actualiza a cada Δt seg.

Arquitecturas

Redes recurrentes o estructuras

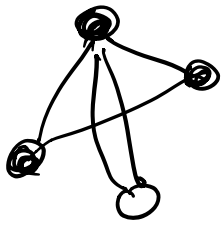




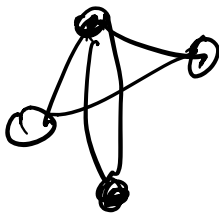
El input es el estado inicial

$$\{y_i(t=0)\}_{i=1}^N$$

$$y_i = \begin{cases} +1 & \bullet \\ -1 & \circ \end{cases}$$



$t=0$



$t=1$





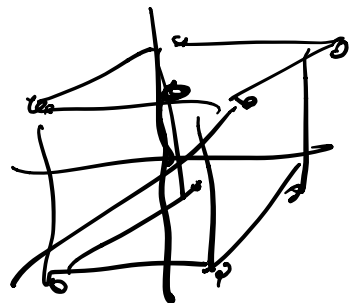
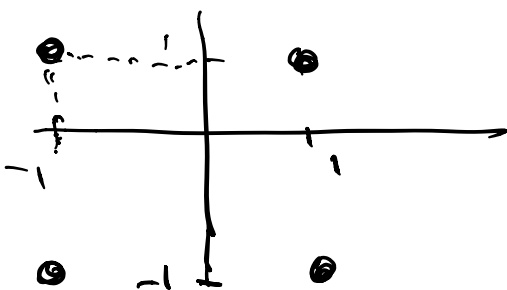
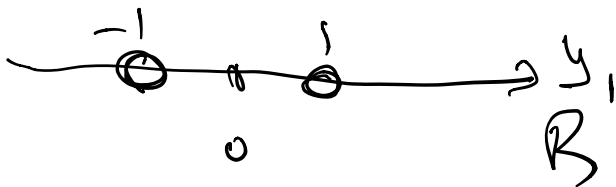
$t=2$

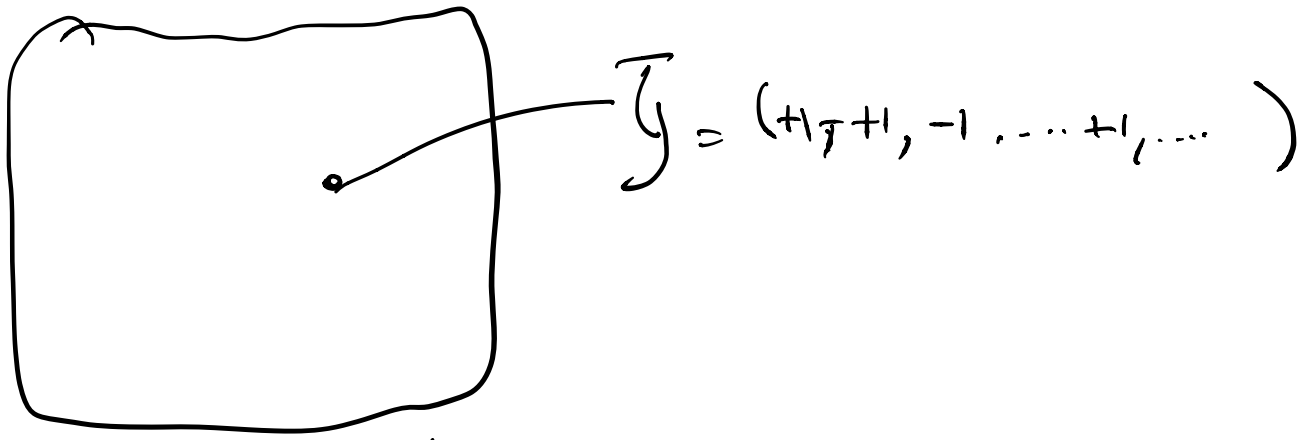
input $\{y_i(0)\}_{i=1}^N \rightarrow \{y_i(1)\}_{i=1}^N \rightarrow \{y_i(2)\}_{i=1}^N$

$\rightarrow \{y(t=\infty)\}_{i=1}^N$

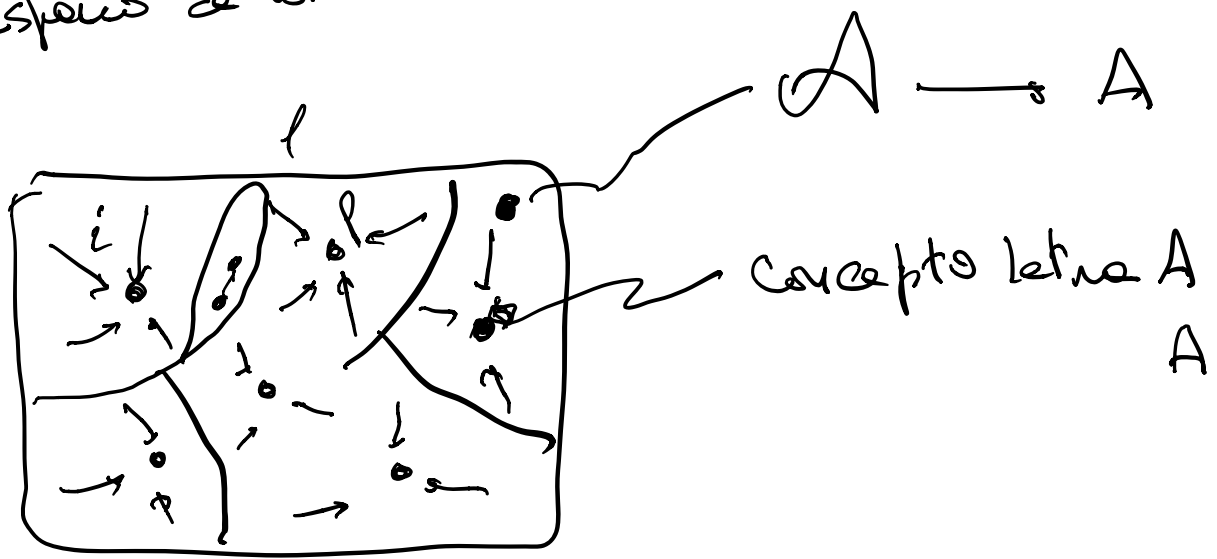
Si tengo N neuronas binarias
¿cuántos estados tengo?

$$\begin{aligned} \text{tengo } 2^N &= e^{\ln 2^N} \\ &= e^{N(\ln 2)} \end{aligned}$$





Espacio de los estados

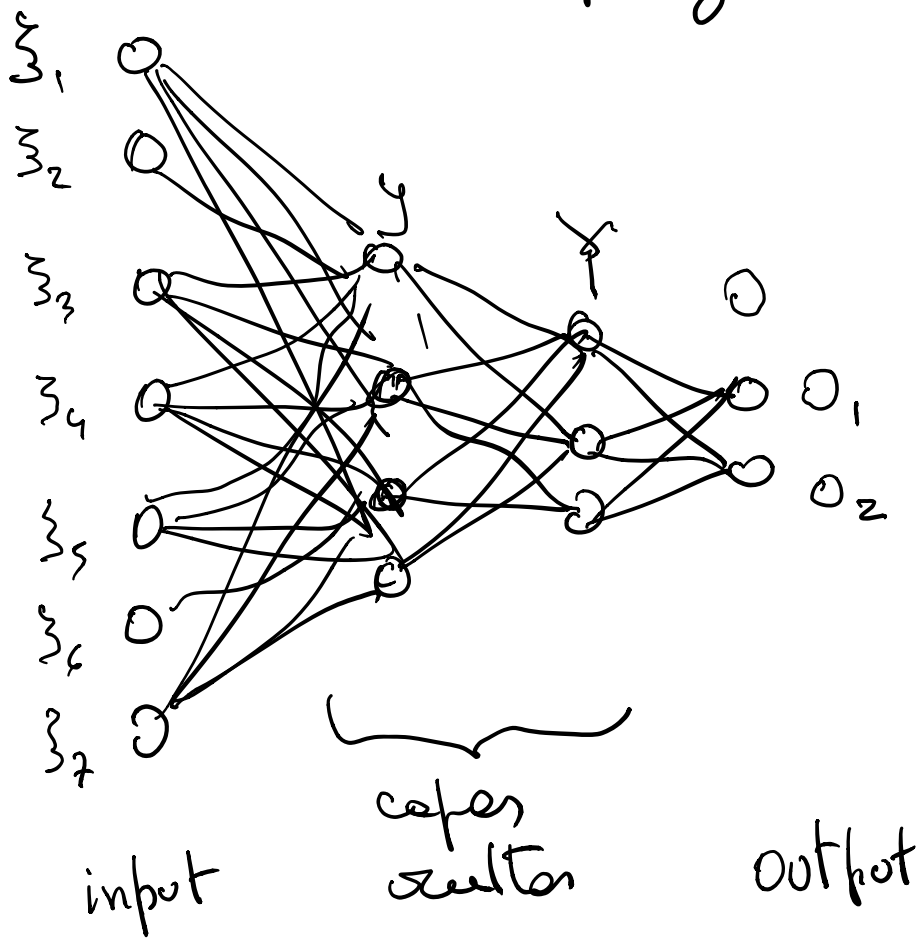


Buscando una solución

Muchos o pocos estados iniciales
atractores

Redes feed forward


los neuronas se organizan en capas



```

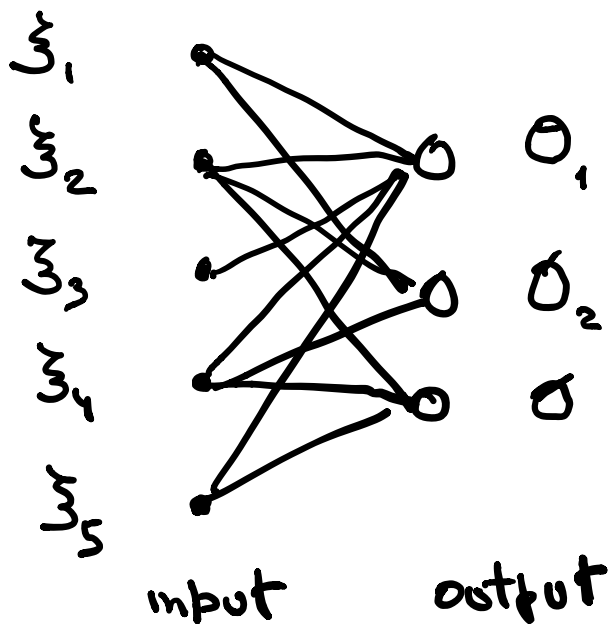
for t := 0 to t_max
  for i := 1 to N
    h := 0
    for k := 1 to P
      h := h + w(i, k) y(k)
    end
    y(i) = F(h - μ)
  end
end

```



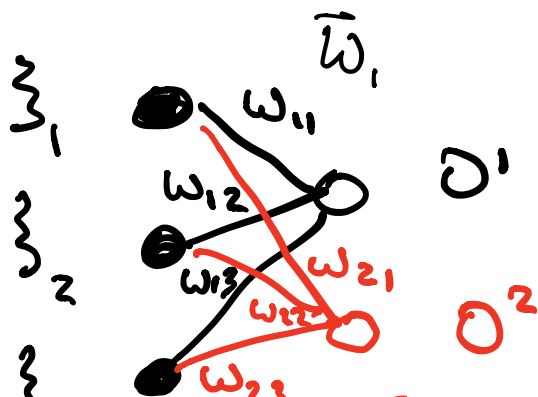
Perceptron simple

tiene una capa de entrada y otra de salida



Puedo desacoplar la red en tres redes

En general, si la capa de salida tiene M neuronas, puedo desacoplar el problema en M perceptrones simples



w_3 w_2



Entonces pensemos por ahora en
una única neurona de salida por
vez, y la llamemos i

Calculamos
$$h_i = \sum_{k=1}^N w_{ik} \xi_k$$

Comparamos h_i con el umbral μ_i

Apliquemos la función $g(h_i - \mu_i)$.

$$O_i = g(h_i - \mu_i)$$

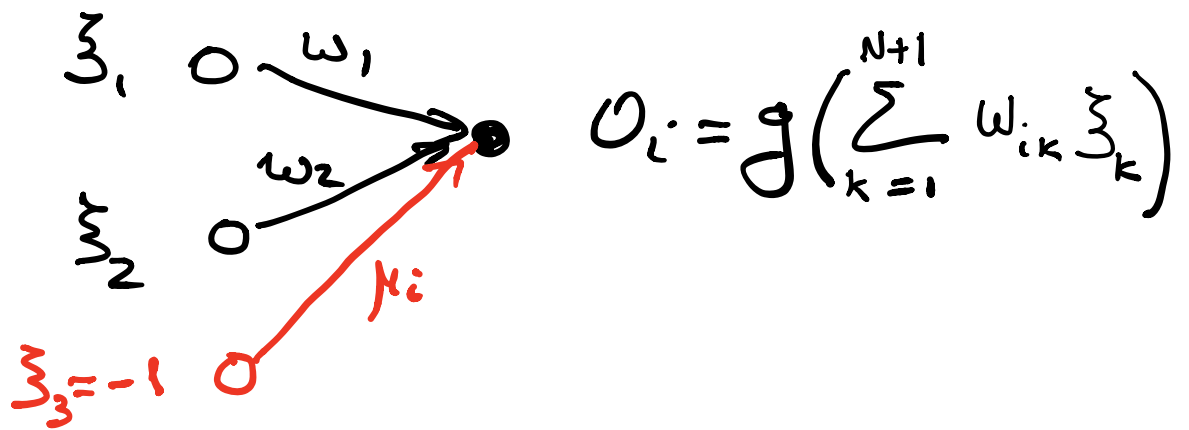
Ahora me libero de μ_i

Agregamos una neurona $N+1$ en
la entrada que siempre vale -1

$$\xi_{N+1} = -1 \quad \text{fija}$$

Dis...

Objetivo $w_{i,N+1} = \mu_i$



Supongamos que tenemos P ejemplos correctos (relaciones input-output)

$$\vec{\xi} = (\xi_1, \xi_2, \dots, \xi_{N+1})$$

$\vec{\xi}^M \rightarrow d_i^M$ M etiqueta el conjunto de entrenamiento $M=1, 2, \dots, P$

Si funciona bien

$$O_i = d_i^M = g\left(\sum_k w_{i,k} \xi_k^M\right)$$

Vamos a tratar de encontrar un conjunto $w_{i,1}, w_{i,2}, \dots, w_{i,N}$ tal que

$$g\left(\sum_k w_{ik} \sum_k^M\right) = d_i^M \quad \forall \mu$$

Notación $\bar{w}_i = (w_{i,1}, w_{i,2}, \dots, w_{i,n})$

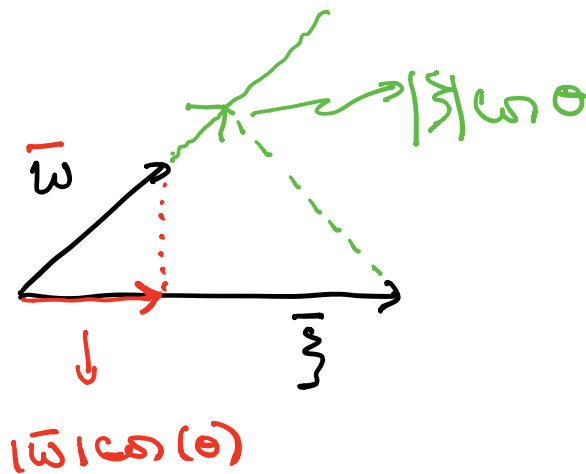
$$\bar{z} = (z_1, z_2, \dots, z_n)$$

$$\bar{z}^M = (z_1^M, z_2^M, \dots, z_n^M)$$

$$\sum_k w_{ik} \sum_k^M = \bar{w}_i \cdot \bar{z}^M = |\bar{w}_i| \cdot |\bar{z}^M| \cos(\theta)$$

↑
producto punto

θ : ángulo que forman los vectores \bar{w}_i y \bar{z}^M

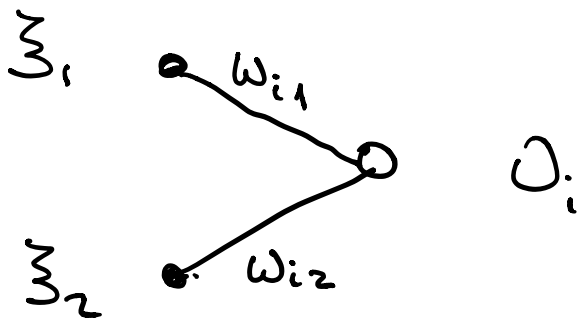


1º Caso : función signo
(unidad de umbral)

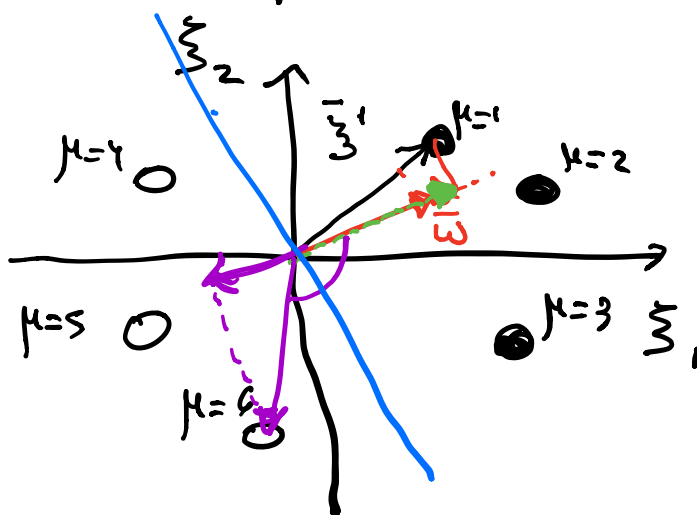
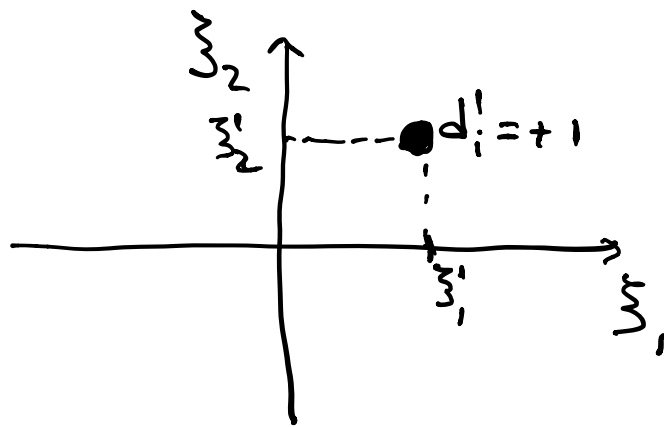
$$g(h) = \begin{cases} +1 & \text{si } h \geq 0 \\ -1 & \text{si } h < 0 \end{cases}$$

Δ los efectos "gráficos" hoy a suaves

$N = 2$.



Tengo 4 ejemplos correctos



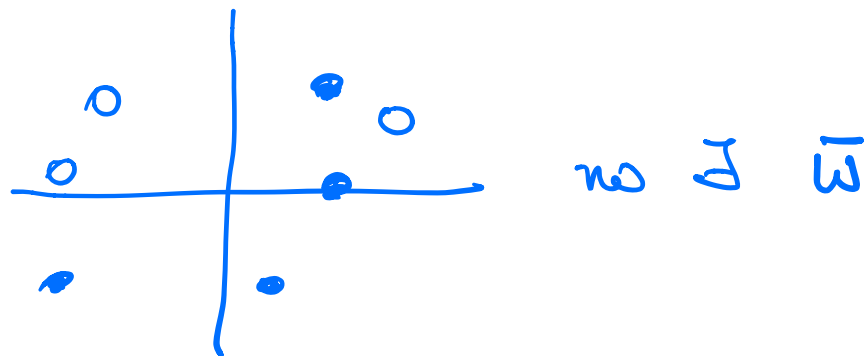
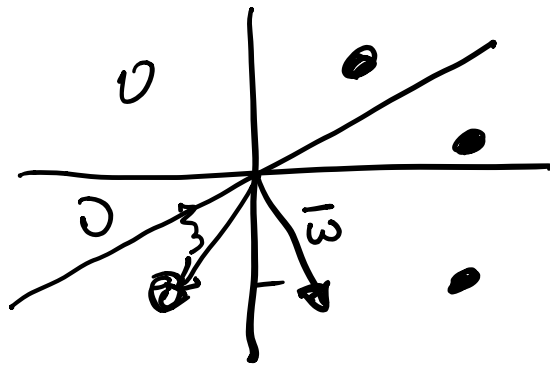
● output $d_i^H = 1$
○ output $d_i^H = -1$

$P = 6$

$$O_i = \text{signo} (\omega_{i1} \bar{x}_1 + \omega_{i2} \bar{x}_2) = d_i^M$$

$$\text{signo} (\bar{w} \cdot \bar{x}) = d_i^M$$

$$\text{Si } d_i^M = +1 \Rightarrow \bar{w} \cdot \bar{x} > 0$$



Si \exists una recta (hiperplano) que separe los $+1$ de los -1 , entonces \exists un vector \bar{w} que hace funcionar bien el perceptron

Si no \exists esa recta (hiperplano), no tiene solución el problema

Podemos definir $X_k^H = d_i^H \sum_k^H$

$$\bar{X}^H = d_i^H \bar{\sum}^H$$

$$d_i^H = \pm 1$$

$\bar{X} \cdot \bar{Y} \cdot a$

$$\text{sig}(\bar{w} \cdot \bar{\sum}^H) = \pm 1 = d_i^H$$

$\bar{X} \cdot (a\bar{Y})$

$$\text{sig}(\bar{w} \cdot \bar{\sum}^H) d_i^H = (d_i^H)^2 = 1$$

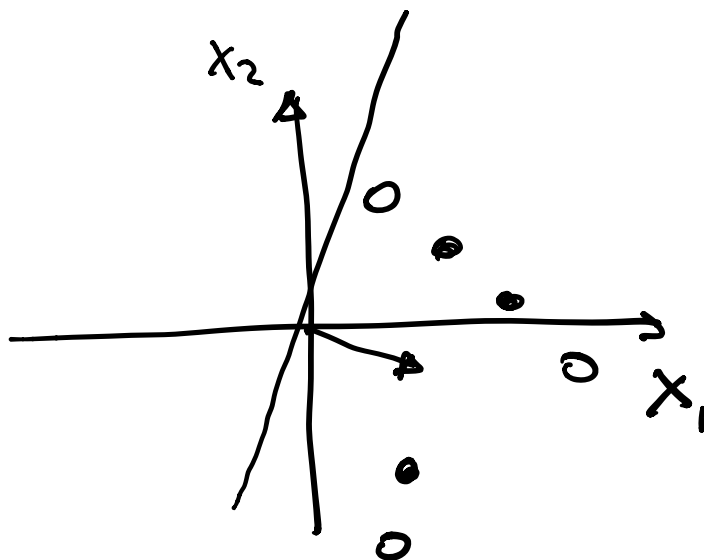
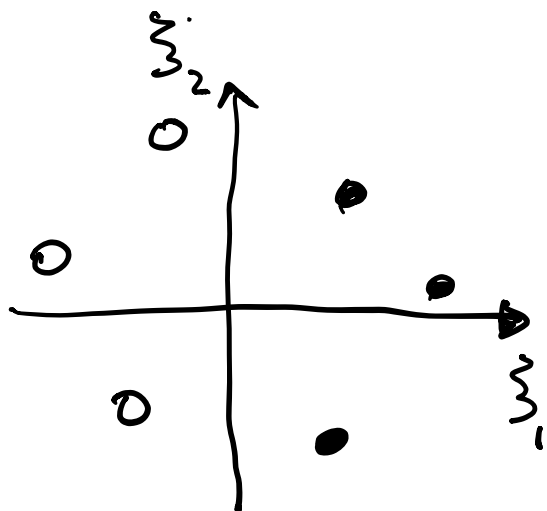
$$\text{sig}((\bar{w} \cdot \bar{\sum}^H) d_i^H) = 1$$

$$\text{sig}(\bar{w} \cdot (\bar{\sum}_i^H d_i^H)) = 1$$

$$\text{sig}(\bar{w} \cdot \bar{X}^H) = 1 \quad \leftarrow$$



$$\bar{w} \cdot \bar{X}^H > 0$$



Para que un problema de clasificación ± 1 se pueda resolver, debe ser "linealmente separable" (LS)

Si no es LS no significa que no exista una red que lo resuelva. Solo problemas que no pueden ser un perceptron simple.

"Volviendo a poner el Umbral"

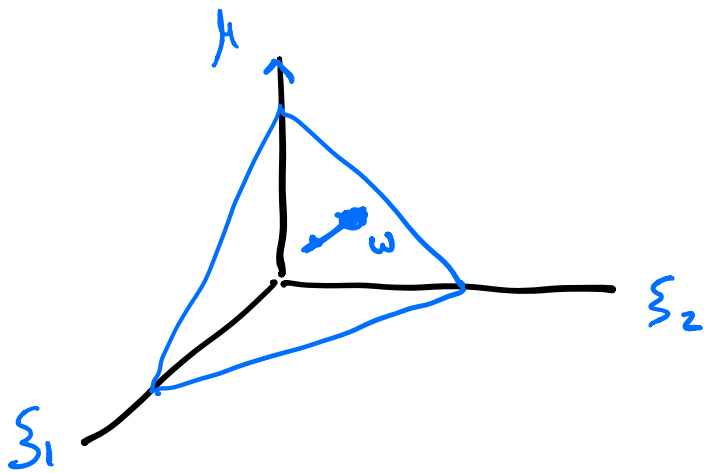
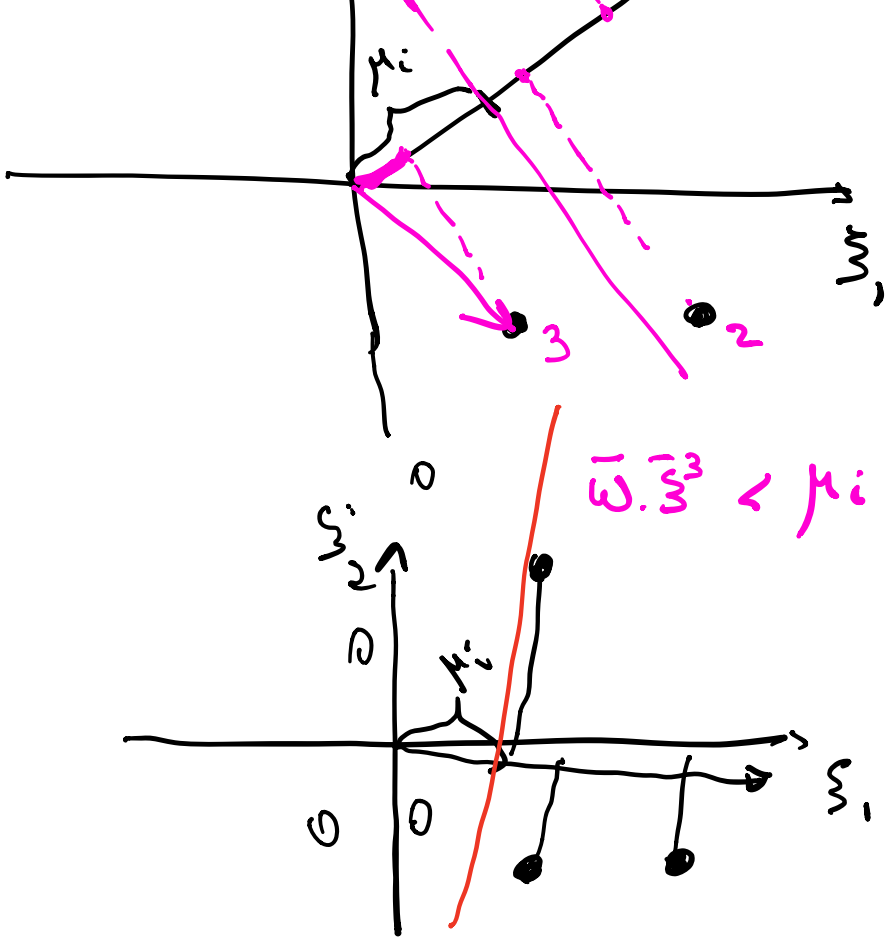
Si hay umbral

$$O_i = \text{signo}(\bar{w} \cdot \bar{x}_i - \mu_i)$$

$\bar{w} \cdot \bar{x}_i = \mu_i$ define la separatriz

$$\begin{array}{ll} \text{si } d_i^M = 1 & \bullet \quad \bar{w} \cdot \bar{x}_i > \mu_i \\ d_i^M = -1 & \circ \quad \bar{w} \cdot \bar{x}_i < \mu_i \end{array}$$

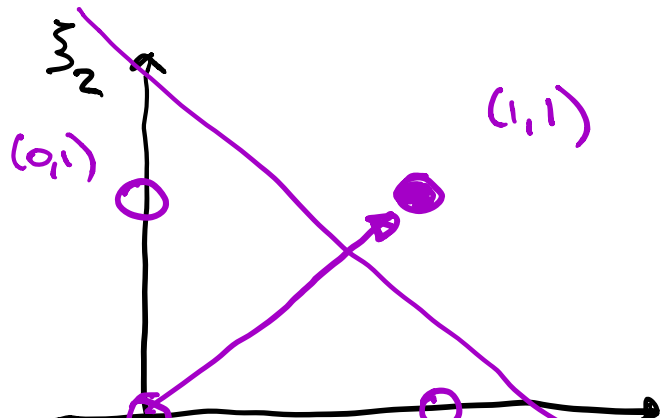




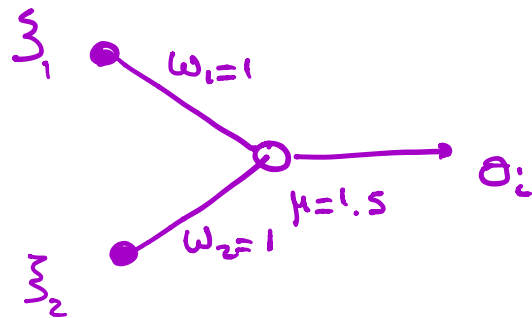
La función IND

- $\mu=1$
- $\mu=2$
- $\mu=3$
- $\mu=4$

ξ_1	ξ_2	d
0	0	-
0	1	-
1	0	-
1	1	-



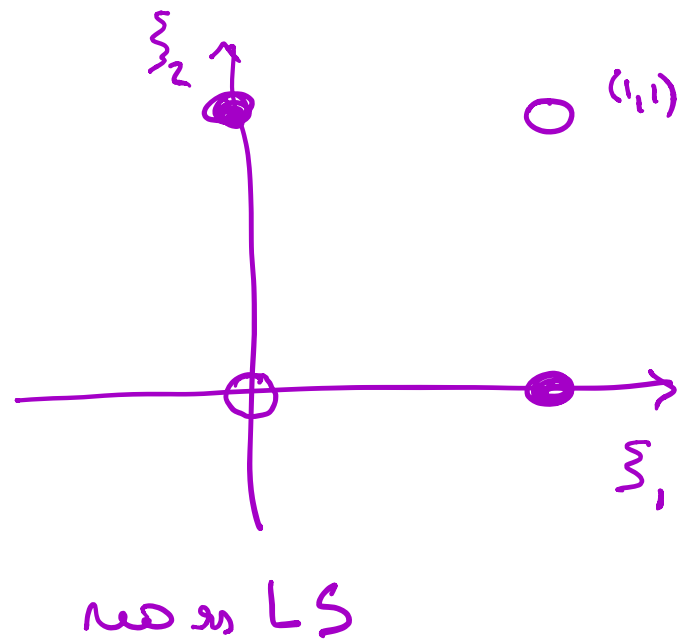
$$\bar{w} = (1, 1)$$



¿fue demostró Minusly?

XOR

z_1	z_2	d
1	1	-1
1	0	1
0	1	1
0	0	-1

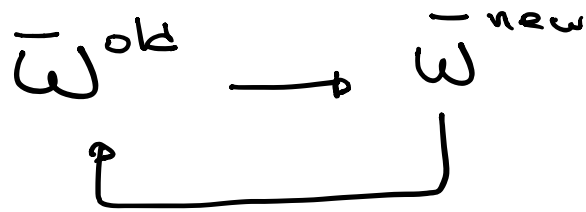


UN ALGORITMO SIMPLE

Supongamos que el problema es L.S.

Buscamos un algoritmo tal que

partiendo de un \bar{w}^0 tomados el
 azar, nos lleve a un \bar{w}^* que
 resuelva el problema EN UN NÚMERO
 FINITO DE PASOS



$$\bar{w}_i^{\text{new}} = \bar{w}_i^{\text{old}} + \Delta \bar{w}_i$$

Secuencialmente le muestra cada
 ejemplo $\mu=1, \mu=2, \dots, \mu=P$.

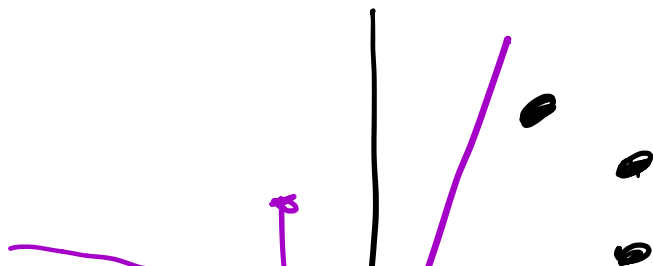
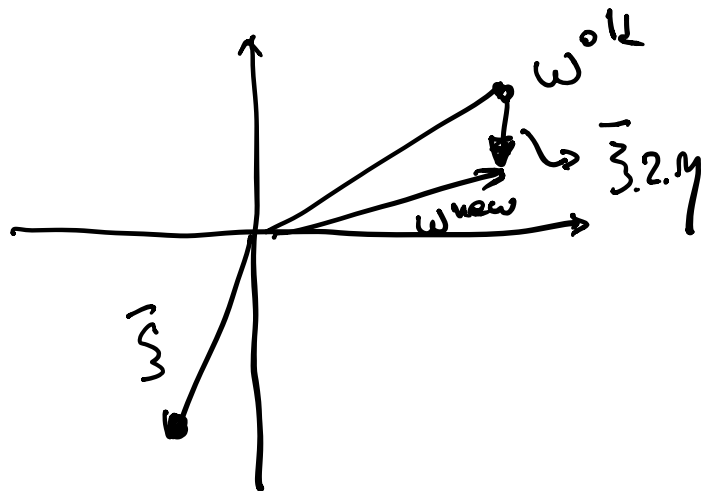
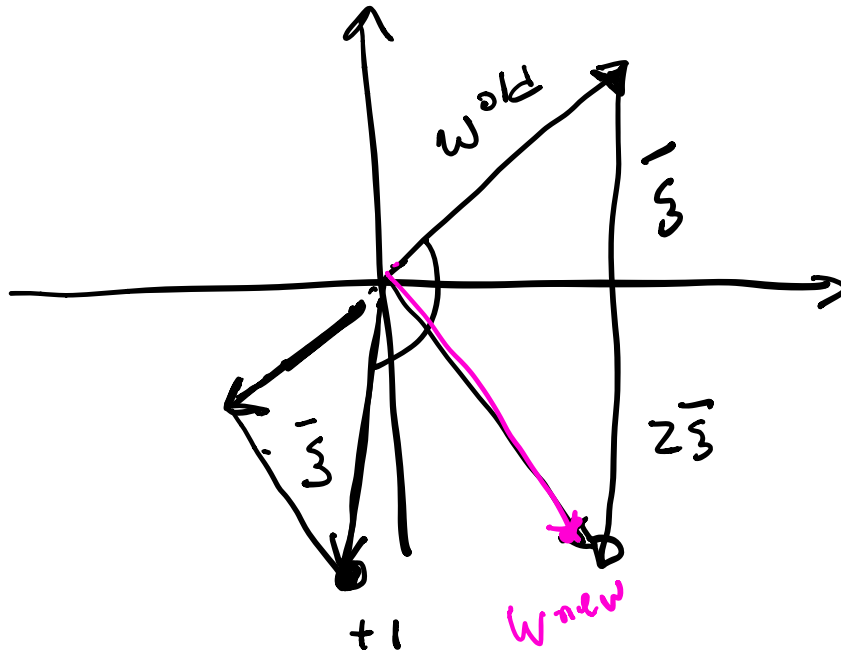
Mientras $\mu=1$. Calculamos O_i^{μ} η (etc)

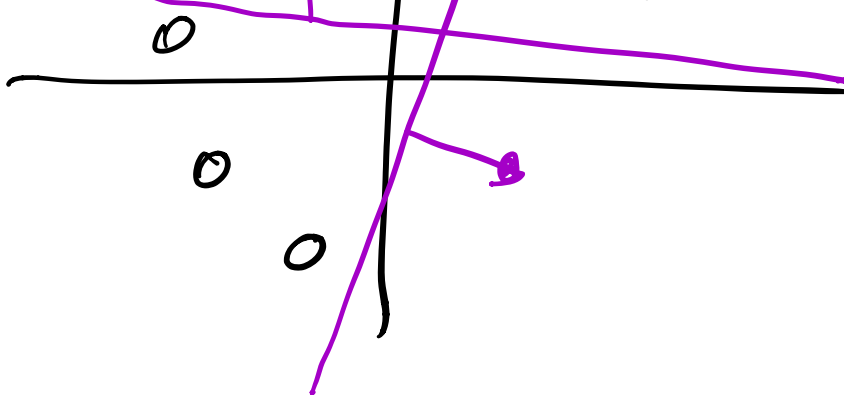
Si $O_i^{\mu} = d_i^{\mu}$ no hay nada

$$O_i^{\mu} \neq d_i^{\mu} \quad \Delta w_{ik} = 2\eta d_i^{\mu} \sum_k^{\mu}$$

$$\Delta w_{ik} = \begin{cases} 2\eta d_i^{\mu} \sum_k^{\mu} & \text{si } O_i^{\mu} \neq d_i^{\mu} \\ 0 & \text{si } O_i^{\mu} = d_i^{\mu} \end{cases}$$

$$\begin{aligned} \Delta w_{ik} &= \eta (1 - d_i^H O_i^H) d_i^H \sum_k^M \\ &= \eta (d_i^H - (d_i^H)^2 O_i^H) \sum_k^M \\ &= \eta (d_i^H - O_i^H) \sum_k^M \end{aligned}$$





$$D(\bar{w}) = \min_{\mu} \bar{w} \bar{\Sigma}^{\mu} / |\bar{w}|$$

El mejor \bar{w} es el que maximiza D

$$D_{\max} = \max_{\bar{w}} D(\bar{w})$$