

UN EJEMPLO ECOLÓGICO SIMPLE

Consideremos un problema de ecología en el cual dos especies compiten por un único recurso alimenticio. Es un caso particular de ecuación de LOTKA-VOLTERRA. Así no hay predadores y presas.

1. Cada especie, en forma ecológicamente aislada, está descrita por una ecuación logística
2. La presencia de la otra especie le quita alimento a cada una.

Ecuaciones:

$$\begin{aligned}\dot{x} &= x(3-x) - 2xy \\ \dot{y} &= y(2-y) - xy\end{aligned}$$

no linealidad

$x(t)$: población de conejos.

$y(t)$: población de ovejas.

$$x \geq 0 \quad \text{e} \quad y \geq 0$$

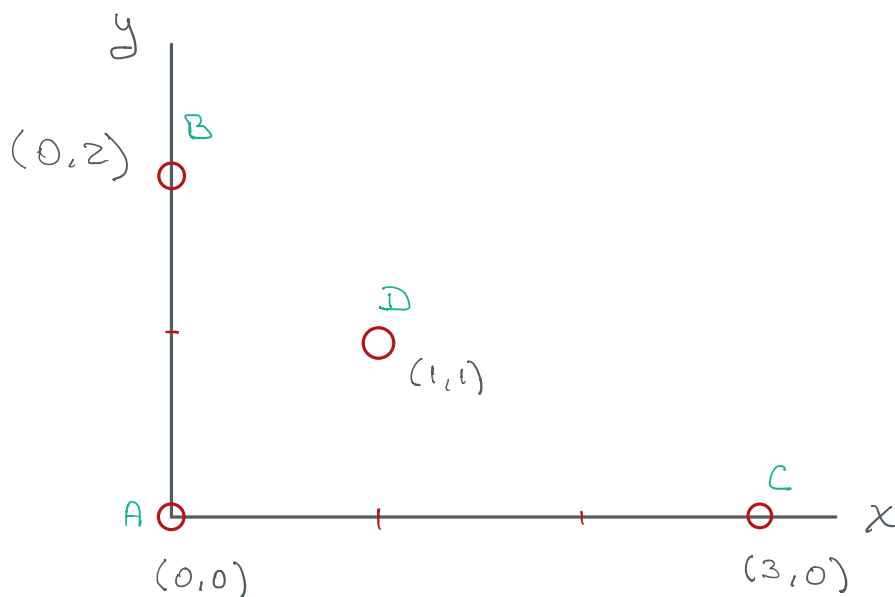
Ahora miremos los puntos fijos

A $(0,0)$

B $(0,2)$

C $(3,0)$

D $(1,1)$



Ahora linealizamos:

$$A = \begin{vmatrix} \frac{\partial \dot{x}}{\partial x} & \frac{\partial \dot{x}}{\partial y} \\ \frac{\partial \dot{y}}{\partial x} & \frac{\partial \dot{y}}{\partial y} \end{vmatrix}$$
$$= \begin{vmatrix} 3 - 2x - y & -2x \\ -y & 2 - x - 2y \end{vmatrix}$$

A) $\bar{x}^* = (0, 0)$

$$A_{(0,0)} = \begin{vmatrix} 3 & 0 \\ 0 & 2 \end{vmatrix}$$

$$\lambda_1 = 3 \quad \lambda_2 = 2$$

$$\bar{v}_1 = (1, 0) \quad \bar{v}_2 = (0, 1)$$

$(0, 0)$ es un punto fijo inestable (modo).

$$B) \quad \bar{x}^* = (0, 2)$$

$$A_{(0,2)} = \begin{vmatrix} 3-4 & 0 \\ -2 & 2-4 \end{vmatrix} = \begin{vmatrix} -1 & 0 \\ -2 & -2 \end{vmatrix}$$

$$\det(A - \lambda I) = \det \begin{vmatrix} -1-\lambda & 0 \\ -2 & -2-\lambda \end{vmatrix} = 0$$

$$= (1+\lambda)(2+\lambda)$$

$$= 2 + 3\lambda + \lambda^2$$

$$= \lambda^2 + 3\lambda + 2$$

$$\lambda_1 = \frac{-3 + \sqrt{9-8}}{2} = \frac{-3+1}{2} = -1$$

$$\lambda_2 = \frac{-3 - \sqrt{9-8}}{2} = \frac{-3-1}{2} = -2$$

$(0, 2)$ es un punto fijo estable

Part $\lambda = -1$

$$A \bar{x} = -\bar{x} \Rightarrow \begin{pmatrix} -1 & 0 \\ -2 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -x \\ -y \end{pmatrix}$$

$$-x = -x$$

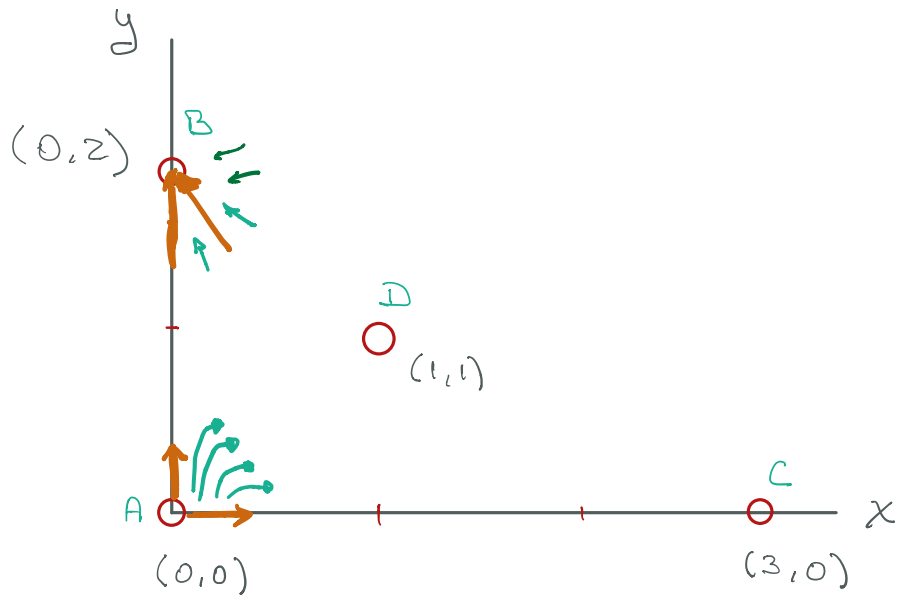
$$-2x - 2y = -y \Rightarrow -2x = y$$

Si $x = 1$, entonces $y = -2$ $\bar{v}_1 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$

Part $\lambda = -2$

$$A \bar{x} = \begin{pmatrix} -1 & 0 \\ -2 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = - \begin{pmatrix} 2x \\ 2y \end{pmatrix}$$

$$-2x - 2y = 2y \Rightarrow x = 0 \quad \bar{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



c) si $\bar{x}^* = (3, 0)$

$$\det(A - \lambda I) = \det \begin{pmatrix} -3 - \lambda & -6 \\ 0 & -1 - \lambda \end{pmatrix} = (3 + \lambda)(1 + \lambda) = \lambda^2 + 4\lambda + 3 = 0$$

$$\lambda_1 = \frac{-4 + \sqrt{16 - 12}}{2} = -\frac{4 + 2}{2} = -1$$

$$\lambda_2 = \frac{-4 - \sqrt{16 - 12}}{2} = -\frac{4 - 2}{2} = -3$$

$$\text{Si } \lambda_1 = -3$$

$$A \bar{x} = \begin{pmatrix} -3 & -6 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = -3 \begin{pmatrix} x \\ y \end{pmatrix}$$

$$-3x - 6y = -3x \Rightarrow y = 0 \quad \vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

nápida

$$\text{Si } \lambda_2 = -1$$

$$A \bar{x} = \begin{pmatrix} -3 & -6 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = - \begin{pmatrix} x \\ y \end{pmatrix}$$

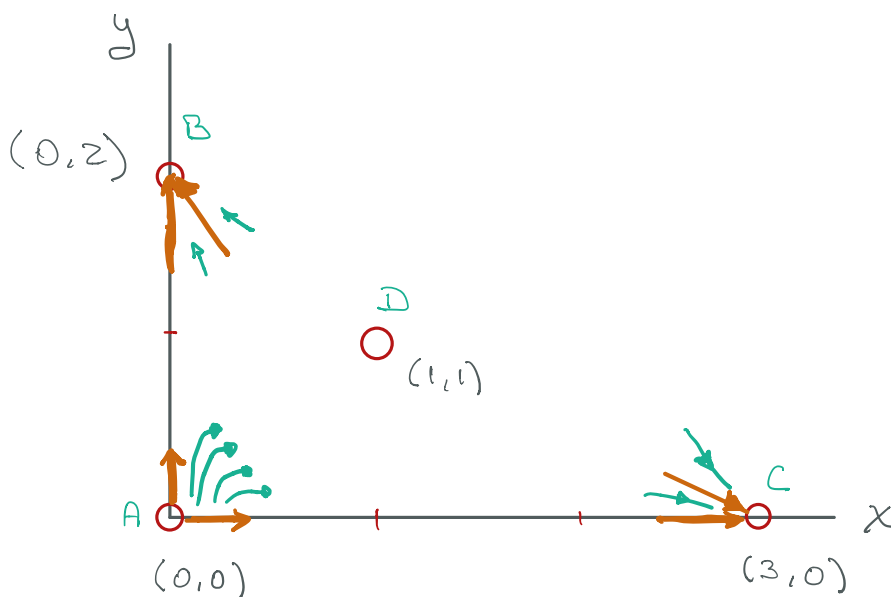
$$-3x - 6y = -x$$

$$-2x = 6y$$

$$y = -\frac{1}{3}x$$

$$\vec{v}_2 = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

lento



$$D) \text{ si } \bar{X}^* = (1, 1)$$

$$A = \begin{pmatrix} -1 & -2 \\ -1 & -1 \end{pmatrix}$$

$$\begin{aligned} \det(A - \lambda I) &= \det \begin{pmatrix} -1-\lambda & -2 \\ -1 & -1-\lambda \end{pmatrix} = (1+\lambda)^2 - 2 \\ &= \lambda^2 - 2\lambda + 1 - 2 \\ &= \lambda^2 - 2\lambda - 1 = 0 \end{aligned}$$

$$\lambda_1 = \frac{2 + \sqrt{4+4}}{2} = \frac{2 + 2\sqrt{2}}{2} = 1 + \sqrt{2} > 0$$

$$\lambda_2 = \frac{2 - \sqrt{8}}{2} = \frac{2 - 2\sqrt{2}}{2} = 1 - \sqrt{2} < 0$$

$(1, 1)$ es un punto de equilibrio (saddle node)

$$\text{Si } \lambda_1 = 1 + \sqrt{2}$$

$$A \bar{X} = \begin{pmatrix} -1 & -2 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = (1 + \sqrt{2}) \begin{pmatrix} x \\ y \end{pmatrix}$$

$$-x - 2y = x + \sqrt{2}x$$

$$-x - y = y + \sqrt{2}y$$

$$-x(2+\sqrt{2}) = -2x - \sqrt{2}x = 2y$$

$$-x = 2y + \sqrt{2}y = y(2+\sqrt{2})$$

$$\text{Si } x=1 \quad 2y = -(2+\sqrt{2})$$

$$y = -\frac{(2+\sqrt{2})}{2}$$

$$\vec{v}_1 = \begin{pmatrix} 1 \\ -\frac{(2+\sqrt{2})}{2} \end{pmatrix}$$

$$\text{Si } \lambda_1 = 1 - \sqrt{2}$$

$$A \begin{pmatrix} x \\ y \end{pmatrix} = (1 - \sqrt{2}) \begin{pmatrix} x \\ y \end{pmatrix}$$

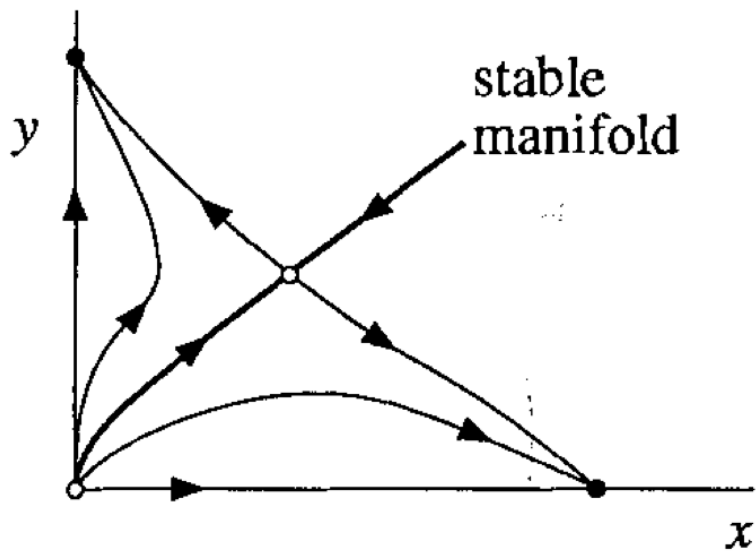
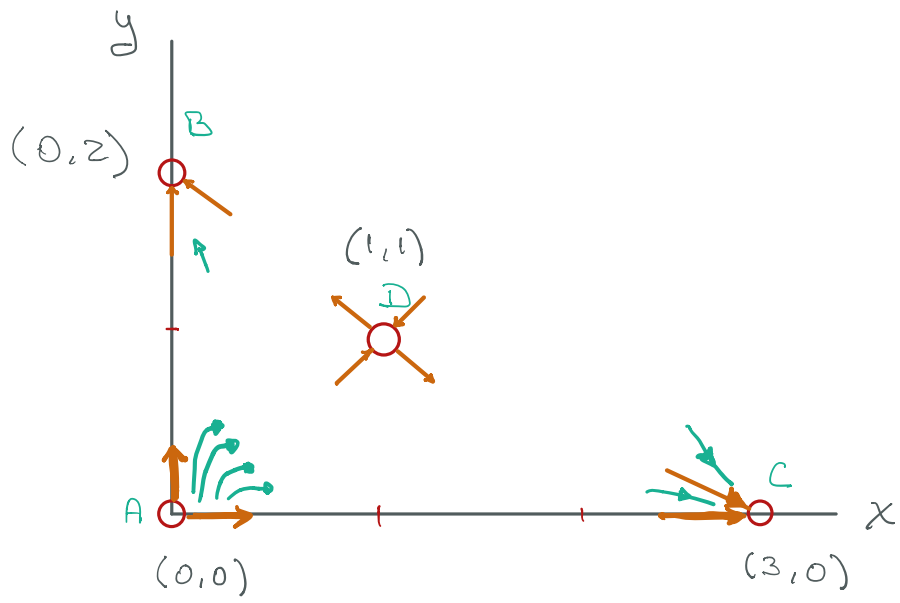
$$-x - 2y = (1 - \sqrt{2})x$$

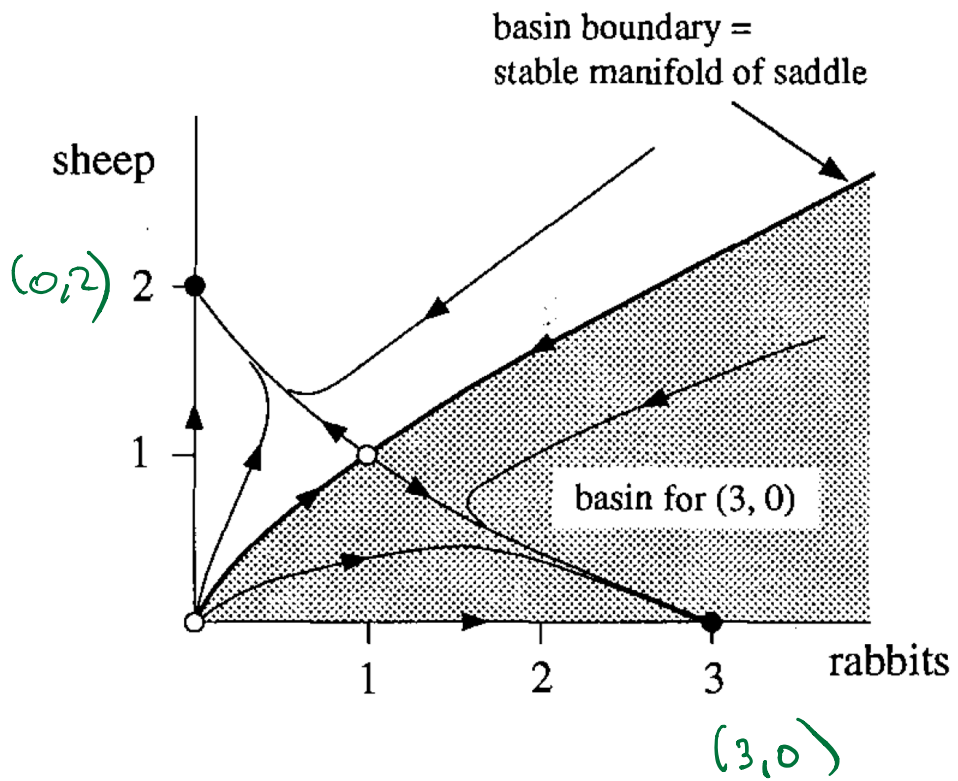
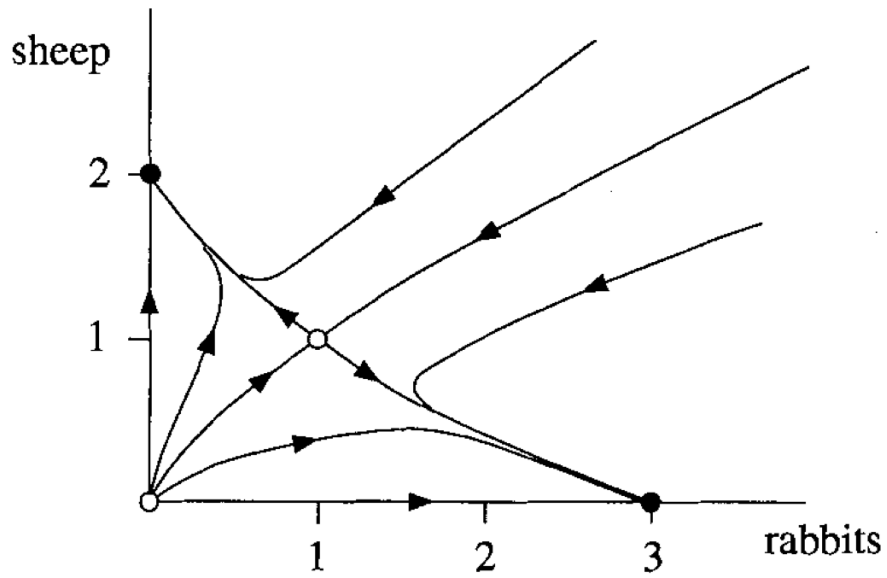
$$-2x + \sqrt{2}x = 2y$$

$$\text{Si } x=1 \Rightarrow -2 + \sqrt{2} = 2y$$

$$y = \left(\frac{-2 + \sqrt{2}}{2} \right) \Rightarrow$$

$$\vec{v}_2 = \begin{pmatrix} 1 \\ -\left(\frac{2 - \sqrt{2}}{2} \right) \end{pmatrix}$$





BIFURCACIONES REVISITADAS EN 2D

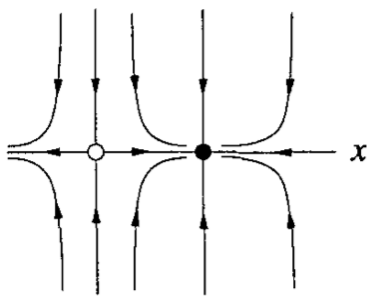
SADDLE NODE

$$\left. \begin{aligned} \dot{x} &= \mu - x^2 \\ \dot{y} &= -y \end{aligned} \right\} \text{forma normal}$$

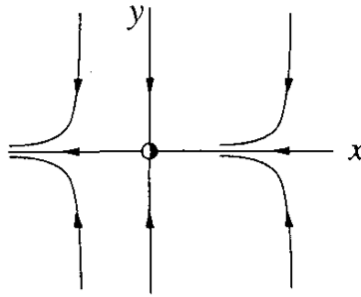
Punto fijo

$$(x^*, y^*) = (\sqrt{\mu}, 0)$$

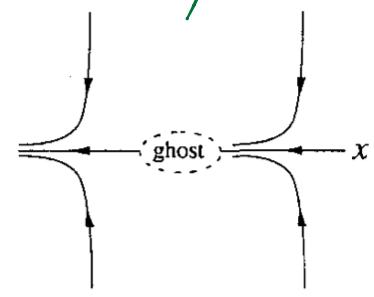
$$\propto (\mu - \mu_c)^{-1/2}$$



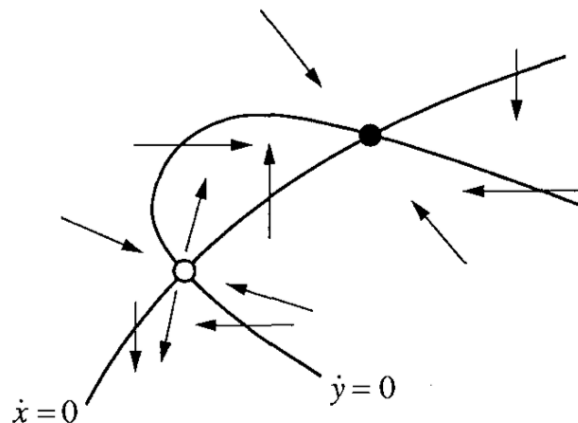
$\mu > 0$



$\mu = 0$



$\mu < 0$



EJEMPLO

$$\dot{x} = -ax + y$$

x : concentración de proteínas

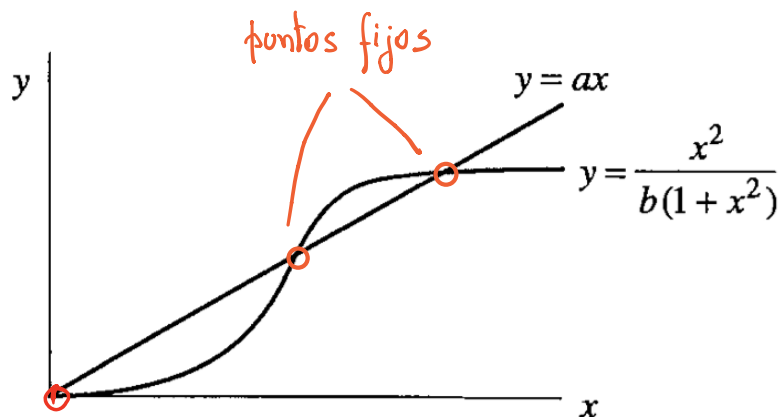
$$\dot{y} = \frac{x^2}{1+x^2} - by$$

y : concentración de RNA

Los nullclines son

$$y = ax$$

$$y = \frac{x^2}{b(1+x^2)}$$



Estos curvas se intersectan cuando

$$ax = \frac{x^2}{b(1+x^2)}$$

$$x^* = 0 \quad \text{e} \quad y^* = 0$$

la otra solución es

$$ab(1+x^2) = x$$

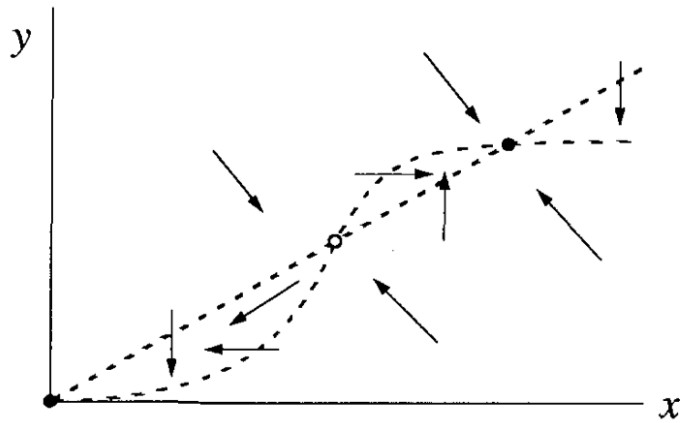
$$x_{\pm}^* = \frac{1 \pm \sqrt{1-4a^2b^2}}{2ab},$$

si $1-4a^2b^2 > 0$ o $2ab < 1$. Las dos curvas colapsan cuando

$$ac = \frac{1}{2b}$$

$$x^* = 1$$

$$\begin{aligned} x^* &= \frac{1 \pm \sqrt{1-4b^2/4b^2}}{2b/2b} \\ &= \frac{1 \pm \sqrt{1-1}}{1} = 1 \end{aligned}$$



$$A = \begin{pmatrix} -a & 1 \\ \frac{2x}{(1+x^2)^2} & -b \end{pmatrix}$$

$$\zeta = -(a+b) < 0$$

$$(x^*, y^*) = (0, 0) \Rightarrow \Delta = ab > 0 \quad \text{nodo estable}$$

$$\zeta^2 - 4\Delta = (a-b)^2 > 0$$

Para los otros dos puntos:

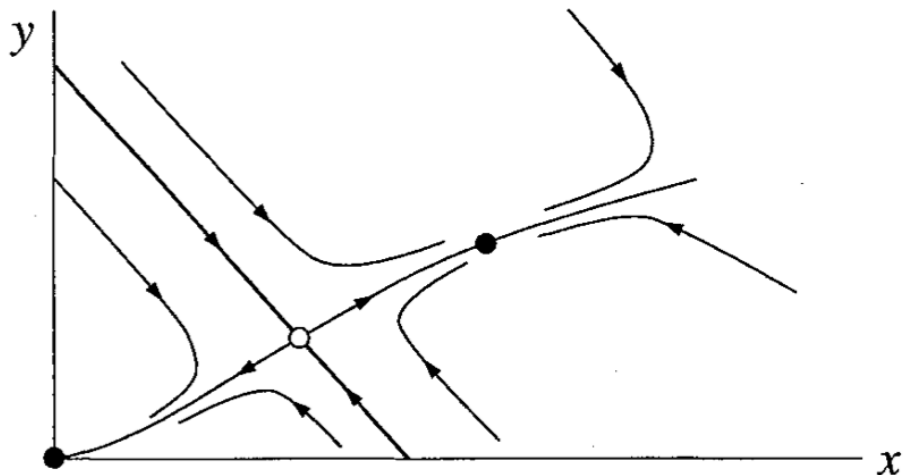
$$\Delta = ab - \frac{2x^*}{(1+(x^*)^2)^2} = ab \left[\frac{(x^*)^2 - 1}{1+(x^*)^2} \right].$$

Para el punto con $0 < x^* < 1$ (intermedio)

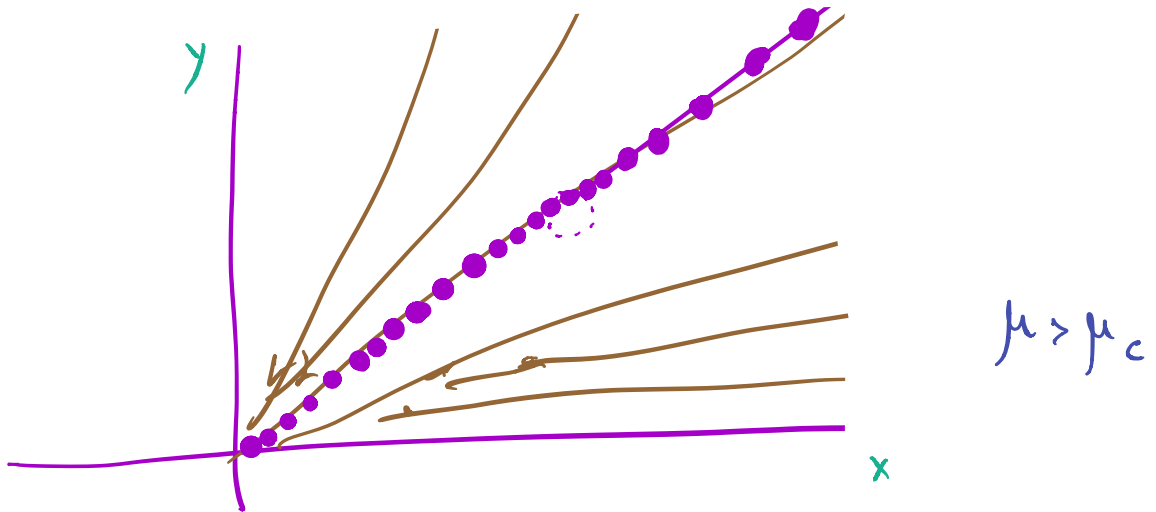
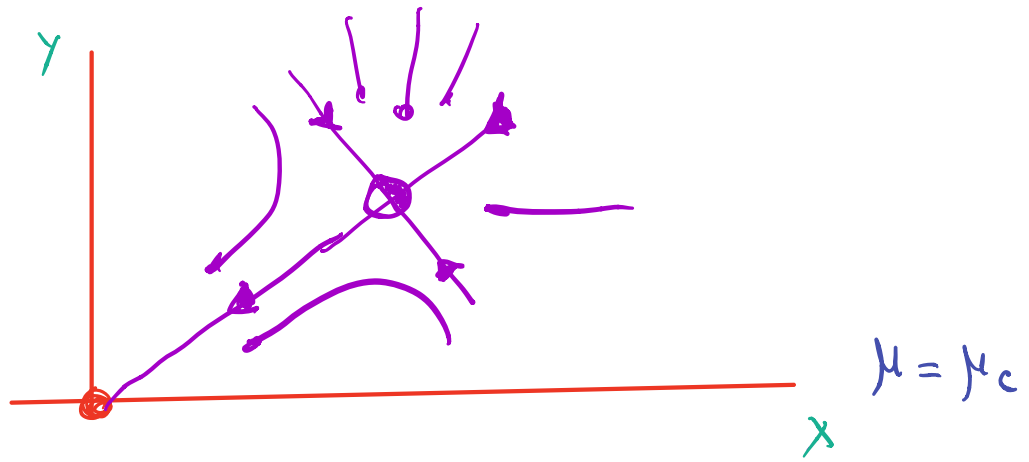
$\Delta < 0$ y el punto fijo es un saddle node.

Para el punto con $x^* > 1$ (derecho)

$\Delta > 0$ y el punto fijo es estable.



$$\mu < \mu_c$$

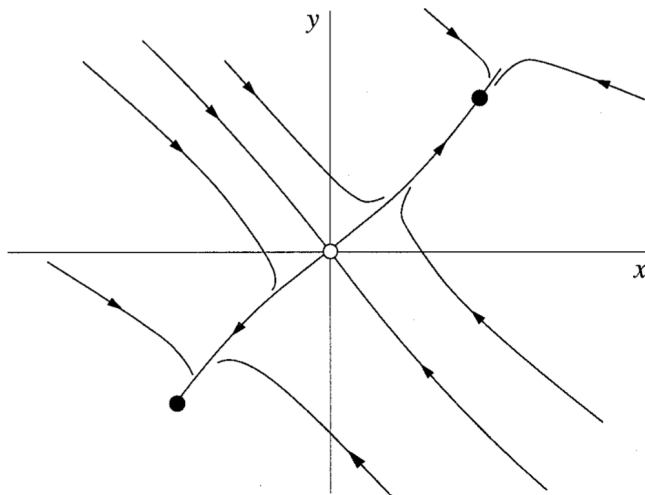
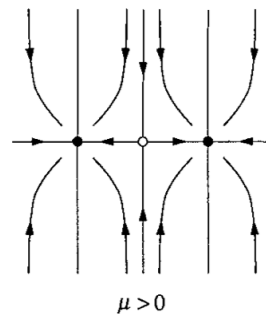
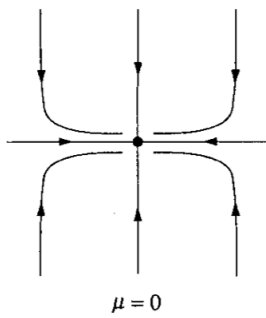
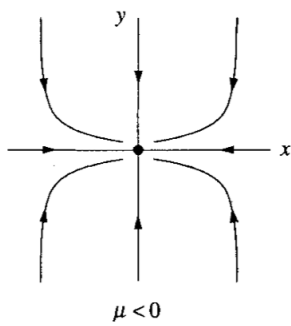


BIFURCACIÓN TRANSCRÍPTICA

$$\dot{x} = \mu x - x^2, \quad \dot{y} = -y$$

BIFURCACIÓN PITCHFORK SUPERCRÍTICA

$$\dot{x} = \mu x - x^3, \quad \dot{y} = -y$$



Ejemplo

$$\dot{x} = \mu x + y + \sin(x)$$

$$\dot{y} = x - y$$

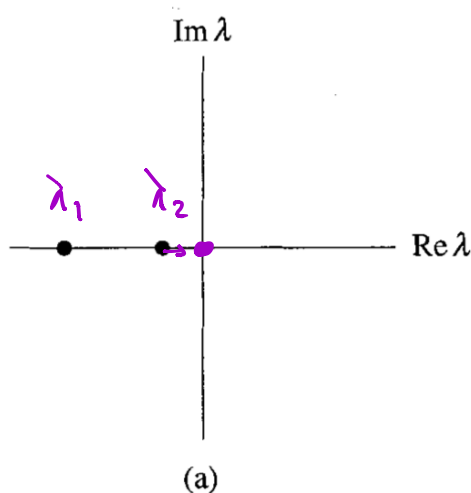
BIFURCACIÓN PITCHFORK SUBCRÍTICA

$$\dot{x} = \mu x + x^3, \quad \dot{y} = -y$$

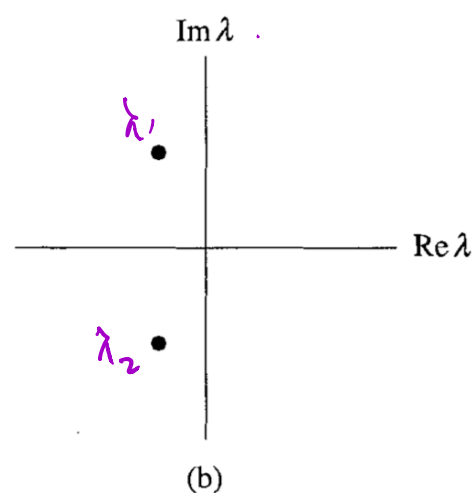
BIFURCACIÓN DE HOPF (NUEVO en 2D)

Supongamos que tenemos un punto fijo estable

$$\operatorname{Re}(\lambda_1) \leq \operatorname{Re}(\lambda_2) < 0$$



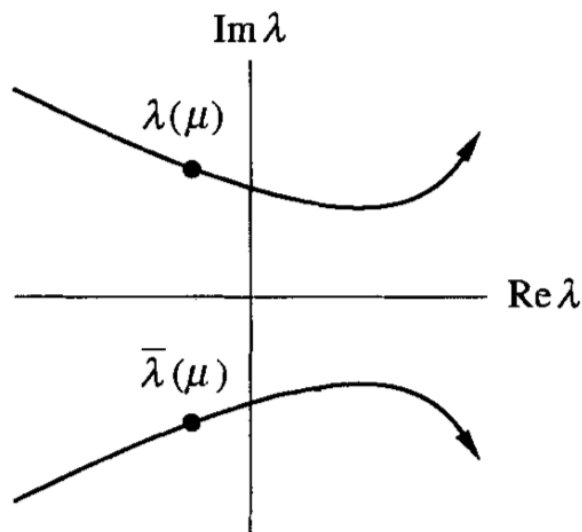
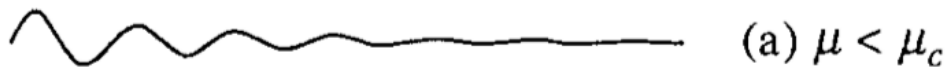
nodos estables



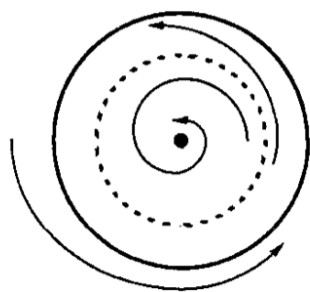
espines estables

Bifurcación supercrítica de Hopf

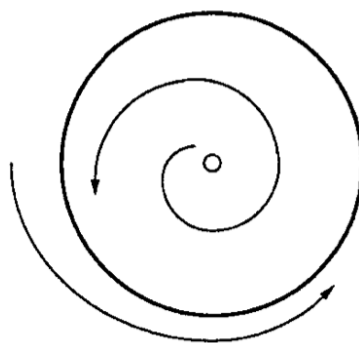
Tenemos originalmente un espiral estable



El parámetro μ controla el paraje de espiral estable o espiral inestable y un ciclo límite

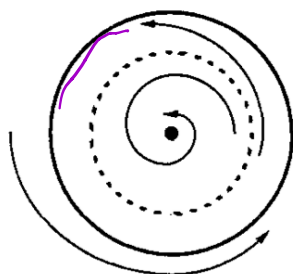


$\mu < 0$

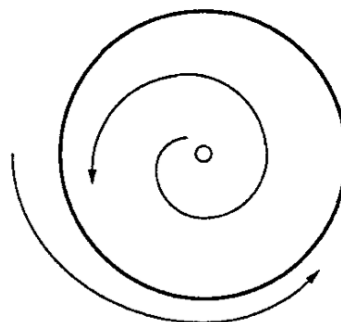


$\mu > 0$

Bifurcación subcrítica de Hopf



$\mu < 0$



$\mu > 0$

Muestra histeresis

