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On rational forms of nilpotent lie algebras

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REPÚBLICA ARGENTINA

ON RATIONAL FORMS OF NILPOTENT LIE ALGEBRAS

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1. INTRODUCTION

When a simply connected nilpotent Lie group N admits a lattice Γ (i.e. a cocompact discrete subgroup), then one can study dynamics on the compact quotient N/Γ (*nilmanifold*), or geometry if one equips N with a left invariant Riemannian metric, complex structure, symplectic structure, etc. Dynamical and geometric properties of N/Γ often depend only on the commensurability class of the lattice Γ . It is then when one runs into the following problem:

(*) To find all rational forms up to isomorphism of a given real nilpotent Lie algebra $\mathfrak{n}.$

There is not much on this question in the literature, and a complete answer seems quite difficult to obtain in explicit examples, even in low dimensional or 2-step nilpotent cases. In [GS, Theorem 3.1], the set of isomorphism classes of rational forms of \mathfrak{n} is described by using Galois cohomology of the group $Gal(\overline{\mathbb{Q}}/\mathbb{Q})$ with values in Aut(\mathfrak{n}). The problem can also be described in terms of rational points in the orbit space of an algebraic variety (see [E, Section 5] and (4)).

We recall that a rational form of \mathfrak{n} is a rational subspace $\mathfrak{n}^{\mathbb{Q}}$ of \mathfrak{n} such that $\mathfrak{n}^{\mathbb{Q}} \otimes \mathbb{R} = \mathfrak{n}$ and $[X, Y] \in \mathfrak{n}^{\mathbb{Q}}$ for all $X, Y \in \mathfrak{n}^{\mathbb{Q}}$. Two rational forms $\mathfrak{n}_{1}^{\mathbb{Q}}$, $\mathfrak{n}_{2}^{\mathbb{Q}}$ of \mathfrak{n} are said to be *isomorphic* if there exists $A \in \operatorname{Aut}(\mathfrak{n})$ such that $A\mathfrak{n}_{1}^{\mathbb{Q}} = \mathfrak{n}_{2}^{\mathbb{Q}}$, or equivalently, if they are isomorphic as Lie algebras over \mathbb{Q} . Not every real nilpotent Lie algebra admits a rational form. By a result due to Malcev, the existence of a rational form of \mathfrak{n} is equivalent to the corresponding Lie group N admits a lattice (see [R]). Another difference with the semisimple case is that sometimes \mathfrak{n} has only one rational form up to isomorphism.

For \mathfrak{n} 2-step nilpotent and with 2-dimensional center, F. Grunewald, D. Segal and L. Sterling [GSS, GS] gave an answer to (*) in terms of isomorphism classes of binary forms. Such a binary form is the *Pfaffian form* of \mathfrak{n} , which is a homogeneous polynomial of degree m in k variables attached to any 2-step nilpotent Lie algebra \mathfrak{n} of dimension 2m + k and dim $[\mathfrak{n}, \mathfrak{n}] = k$ (see Definition 2.2). The projective equivalence class of this form is an isomorphism invariant of \mathfrak{n} (see also [S]).

In Section 4, we show how one can apply Pfaffian forms (Section 2), the results from [GSS, GS] and Scheuneman duality (Section 3), to solve problem (*). We compute explicitly the set of isomorphism classes of rational forms for many 2-step nilpotent Lie algebras over \mathbb{R} and \mathbb{C} . We finally consider in Section 5 a 3-step nilpotent example, for which the above techniques do not apply. We refer to Tables 1 and 2 for a quick look at the results obtained.

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The choice of these particular examples was motivated by the question from dynamical systems of which nilmanifolds admit an Anosov diffeomorphism. The information on rational forms provided in this paper is very useful in the classification of such nilmanifolds in dimension ≤ 8 carried out in [LW].

2. PFAFFIAN FORM

Let \mathfrak{n} be a Lie algebra over the field K, which is assumed from now on to be of characteristic zero. We are mainly interested in the cases $K = \mathbb{C}, \mathbb{R}, \mathbb{Q}$. Fix a non-degenerate symmetric K-bilinear form $\langle \cdot, \cdot \rangle$ on \mathfrak{n} (i.e. an inner product). For each $Z \in \mathfrak{n}$ consider the K-linear transformation $J_Z : \mathfrak{n} \longrightarrow \mathfrak{n}$ defined by

(1)
$$\langle J_Z X, Y \rangle = \langle [X, Y], Z \rangle, \quad \forall X, Y \in \mathfrak{n}.$$

Recall that J_Z is skew symmetric with respect to $\langle \cdot, \cdot \rangle$ and the map $J : \mathfrak{n} \longrightarrow \mathfrak{so}(n, K)$ is K-linear, where n is the dimension of \mathfrak{n} . Equivalently, we may define these maps by fixing a basis $\beta = \{X_1, ..., X_n\}$ of \mathfrak{n} rather than an inner product in the following way: J_Z is the K-linear transformation whose matrix in terms of β has entry ij given by

$$\sum_{k=1}^{n} c_{ij}^{k} x_{k}, \quad \text{where} \quad [X_{i}, X_{j}] = \sum_{k=1}^{n} c_{ij}^{k} X_{k}, \quad Z = \sum_{k=1}^{n} x_{k} X_{k}.$$

It is easy to see that this definition coincides with the first one if we let $\langle X_i, X_j \rangle = \delta_{ij}$.

If \mathfrak{n} and \mathfrak{n}' are two Lie algebras over K and J, J' are the corresponding maps, relative to the inner products $\langle \cdot, \cdot \rangle$ and $\langle \cdot, \cdot \rangle'$ respectively, then it is easy to see that a linear map $A : \mathfrak{n} \longrightarrow \mathfrak{n}'$ is a Lie algebra isomorphism if and only if

(2)
$$A^t J'_Z A = J_{A^t Z}, \quad \forall Z \in \mathfrak{n}',$$

where $A^t: \mathfrak{n}' \longrightarrow \mathfrak{n}$ is given by $\langle A^t X, Y \rangle = \langle X, AY \rangle'$ for all $X \in \mathfrak{n}', Y \in \mathfrak{n}$.

Definition 2.1. Consider the central descendent series of \mathfrak{n} defined by $C^0(\mathfrak{n}) = \mathfrak{n}$, $C^i(\mathfrak{n}) = [\mathfrak{n}, C^{i-1}(\mathfrak{n})]$. When $C^r(\mathfrak{n}) = 0$ and $C^{r-1}(\mathfrak{n}) \neq 0$, \mathfrak{n} is said to be *r*-step nilpotent, and we denote by $(n_1, ..., n_r)$ the *type* of \mathfrak{n} , where

$$n_i = \dim C^{i-1}(\mathfrak{n})/C^i(\mathfrak{n}).$$

We also take a decomposition $\mathfrak{n} = \mathfrak{n}_1 \oplus ... \oplus \mathfrak{n}_r$, a direct sum of vector spaces, such that $C^i(\mathfrak{n}) = \mathfrak{n}_{i+1} \oplus ... \oplus \mathfrak{n}_r$ for all *i*.

Assume now that \mathfrak{n} is 2-step nilpotent, or equivalently of type (n_1, n_2) . Consider any direct sum decomposition of the form $\mathfrak{n} = V \oplus [\mathfrak{n}, \mathfrak{n}]$, that is, $\mathfrak{n}_1 = V$. If the inner product satisfies $\langle V, [\mathfrak{n}, \mathfrak{n}] \rangle = 0$ then V is J_Z -invariant for any Z and $J_Z = 0$ if and only if $Z \in V$. We define $f : [\mathfrak{n}, \mathfrak{n}] \longrightarrow K$ by

$$f(Z) = \operatorname{Pf}(J_Z|_V), \qquad Z \in [\mathfrak{n}, \mathfrak{n}],$$

where $Pf : \mathfrak{so}(V, K) \longrightarrow K$ is the *Pfaffian*, that is, the only polynomial function satisfying $Pf(B)^2 = \det B$ for all $B \in \mathfrak{so}(V, K)$ and Pf(J) = 1 for

$$J = \left[\begin{array}{cc} 0 & I \\ -I & 0 \end{array} \right].$$

Roughly speaking, $f(Z) = (\det J_Z|_V)^{\frac{1}{2}}$, and so we need dim V to be even in order to get $f \neq 0$. For any $A \in \mathfrak{gl}(V, K)$, $B \in \mathfrak{so}(V, K)$ we have that $\operatorname{Pf}(ABA^t) = (\det A)\operatorname{Pf}(B)$. **Definition 2.2.** We call f the *Pfaffian form* of the 2-step nilpotent Lie algebra \mathfrak{n} .

If dim V = 2m and dim $[\mathbf{n}, \mathbf{n}] = k$ then $f = f(x_1, ..., x_k)$ is a homogeneous polynomial of degree m in k variables with coefficients in K, where $Z = \sum_{i=1}^{k} x_i Z_i$ and $\{Z_1, ..., Z_k\}$ is a fixed basis of $[\mathbf{n}, \mathbf{n}]$. f is also called a form of degree m, when k = 2 or 3 one uses the words binary or ternary and for m = 2 and 3, quadratic and cubic, respectively.

Let $P_{k,m}(K)$ denote the set of all homogeneous polynomials of degree m in k variables with coefficients in K. The group $\operatorname{GL}_k(K)$ acts naturally on $P_{k,m}(K)$ by

$$(A.f)(x_1, ..., x_k) = f(A^{-1}(x_1, ..., x_k)),$$

that is, by linear substitution of variables, and thus the action determines the usual equivalence relation between forms, denoted by $f \simeq g$. In the present paper, we need to consider the following wider equivalence relation.

Definition 2.3. For $f, g \in P_{k,m}(K)$, we say that f is projectively equivalent to g, and denote it by $f \simeq_K g$, if there exists $A \in GL_k(K)$ and $c \in K^*$ such that

$$f(x_1, ..., x_k) = cg(A(x_1, ..., x_k)).$$

In other words, we are interested in projective equivalence classes of forms.

Proposition 2.4. Let $\mathfrak{n}, \mathfrak{n}'$ be two-step nilpotent Lie algebras over the field K. If \mathfrak{n} and \mathfrak{n}' are isomorphic then $f \simeq_K f'$, where f and f' are the Pfaffian forms of \mathfrak{n} and \mathfrak{n}' , respectively.

Proof. Since \mathfrak{n} and \mathfrak{n}' are isomorphic we can assume that $\mathfrak{n} = \mathfrak{n}'$ and $[\mathfrak{n}, \mathfrak{n}] = [\mathfrak{n}', \mathfrak{n}']$ as vector spaces, and then the decomposition $\mathfrak{n} = V \oplus [\mathfrak{n}, \mathfrak{n}]$ is valid for both Lie brackets [,] and [,]'. Any isomorphism satisfies $A[\mathfrak{n}, \mathfrak{n}] = [\mathfrak{n}', \mathfrak{n}']'$, and it is easy to see that there is always an isomorphism A between them satisfying AV = V. It follows from (2) that

$$A^t J'_Z A = J_{A^t Z}, \qquad \forall \ Z \in [\mathfrak{n}, \mathfrak{n}],$$

and since the subspaces V and [n, n] are preserved by A and A^t we have that

$$f'(Z) = cf(A_2^t Z),$$

where $A_2 = A|_{[\mathfrak{n},\mathfrak{n}]}$ and $c^{-1} = \det A|_V$. This shows that $f \simeq_K f'$.

The above proposition says that the projective equivalence class of the form $f(x_1, ..., x_k)$ is an isomorphism invariant of the Lie algebra **n**. We note that this invariant was actually introduced by J. Scheuneman in [S], from a different point of view.

What is known about the classification of forms? Unfortunately, much less than one could naively expect. The case $K = \mathbb{C}$ is as usual the most developed one, and in such a case the understanding of the ring of invariant polynomials $\mathbb{C}[P_{k,m}]^{\mathrm{SL}_k(\mathbb{C})}$ is crucial. A set of generators and their relations for such a ring is known only for small values of k and m, for instance for k = 2 and $m \leq 8$, or k = 3 and $m \leq 3$. We refer to [D] and the references therein for several explicit classification results.

The following well known result will help us to distinguish between projective equivalence classes of forms, and in view of Proposition 2.4, to recognize nonisomorphic two-step nilpotent Lie algebras.

Proposition 2.5. If $f, g \in P_{k,m}(K)$ satisfy

$$f(x_1, ..., x_k) = cg(A(x_1, ..., x_k))$$

for some $A \in \operatorname{GL}_k(K)$ and $c \in K^*$, then

$$Hf(x_1, ..., x_k) = c^k (\det A)^2 Hg(A(x_1, ..., x_k)),$$

where the Hessian Hf of the form f is defined by

$$Hf(x_1,...,x_k) = \det\left[\frac{\partial^2 f}{\partial x_i \partial x_j}\right].$$

3. RATIONAL FORMS

Let \mathfrak{n} be a nilpotent Lie algebra over \mathbb{R} of dimension n.

Definition 3.1. A rational form of \mathfrak{n} is an *n*-dimensional rational subspace $\mathfrak{n}^{\mathbb{Q}}$ of \mathfrak{n} such that

$$[X,Y] \in \mathfrak{n}^{\mathbb{Q}}, \qquad \forall \ X,Y \in \mathfrak{n}^{\mathbb{Q}}.$$

Two rational forms $\mathfrak{n}_1^{\mathbb{Q}}$, $\mathfrak{n}_2^{\mathbb{Q}}$ of \mathfrak{n} are said to be *isomorphic* if there exists $A \in \operatorname{Aut}(\mathfrak{n})$ such that $A\mathfrak{n}_1^{\mathbb{Q}} = \mathfrak{n}_2^{\mathbb{Q}}$, or equivalently, if they are isomorphic as Lie algebras over \mathbb{Q} (recall that $\mathfrak{n}^{\mathbb{Q}} \otimes \mathbb{R} = \mathfrak{n}$). In an analogous way, by considering \mathbb{R} and \mathbb{C} (resp. \mathbb{Q} and \mathbb{C}) instead of \mathbb{Q} and \mathbb{R} , one defines a *real form* (resp. a *rational form*) of a complex Lie algebra.

The problem of finding all isomorphism classes of rational forms for a given real nilpotent Lie algebra is a very difficult one, even in the low dimensional or two-step cases. Very little is known about this problem in the literature (see [E, Section 5] and [Se]).

We now give a first example on how to use Pfaffian forms to study rational forms of 2-step nilpotent Lie algebras. Let $\mathbf{n}^{\mathbb{Q}}$ be a rational nilpotent Lie algebra of type (4,2). If $\mathbf{n}^{\mathbb{Q}} = \mathbf{n}_1 \oplus \mathbf{n}_2$ is the decomposition such that dim $\mathbf{n}_1 = 4$, dim $\mathbf{n}_2 = 2$ and $[\mathbf{n}^{\mathbb{Q}}, \mathbf{n}^{\mathbb{Q}}] = \mathbf{n}_2$, then we consider the Pfaffian form f of $\mathbf{n}^{\mathbb{Q}}$. Thus f is a binary quadratic form, say $f(x, y) = ax^2 + bxy + cy^2$, with $a, b, c \in \mathbb{Q}$. It is proved in [GSS] that the converse of Proposition 2.4 is valid in this case, that is, there is a oneto-one correspondence between isomorphism classes of non-degenerate (i.e. with center equal to \mathbf{n}_2) rational Lie algebras of type (4, 2) and projective equivalence classes of binary quadratic forms with coefficients in \mathbb{Q} . It is well known that these last classes can be parametrized by

 ${f_k(x,y) = x^2 - ky^2 : k \text{ is a square free integer number}}.$

Recall that an integer number is called square free if $p^2 \nmid k$ for any prime p. The set of all square free numbers parametrizes the equivalence classes of the relation in \mathbb{Q} defined by $r \equiv s$ if and only if $r = q^2 s$ for some $q \in \mathbb{Q}^*$. We are considering k = 0a square free number too. If $f_k \simeq_K f_{k'}$ then it follows from Proposition 2.5 that $-4k = -4q^2k'$ for some $q \in \mathbb{Q}^*$, which implies that k = k' if k and k' are square free.

It is easy to check that the Pfaffian form of the Lie algebra $\mathfrak{n}_k^{\mathbb{Q}} = \mathfrak{n}_1 \oplus \mathfrak{n}_2$ defined by

(3)
$$[X_1, X_3] = Z_1, \quad [X_1, X_4] = Z_2, \quad [X_2, X_3] = kZ_2, \quad [X_2, X_4] = Z_1$$

is f_k . For $K = \mathbb{R}$, these Lie algebras can be distinguished only by the sign of the discriminant of f_k , which says that there are only three real Lie algebras of

type (4,2), namely, those of the form $\mathfrak{n}_k^{\mathbb{Q}} \otimes \mathbb{R}$ with k > 0, k = 0 and k < 0, respectively. It is easy to check that $\mathfrak{n}_1^{\mathbb{Q}} \otimes \mathbb{R} \simeq \mathfrak{h}_3 \oplus \mathfrak{h}_3$, where \mathfrak{h}_3 denotes the real 3-dimensional Heisenberg algebra and $\mathfrak{n}_{-1}^{\mathbb{Q}} \otimes \mathbb{R} \simeq \mathfrak{h}_3^{\mathbb{C}}$, the complex 3-dimensional Heisenberg algebra viewed as real. On the other hand, we obtain that there are only two complexifications $\mathfrak{n}_k^{\mathbb{Q}} \otimes \mathbb{C}$, those with $k \neq 0$ and the one with k = 0.

Proposition 3.2. The set of isomorphism classes of rational forms of the Lie algebras $\mathfrak{h}_3 \oplus \mathfrak{h}_3$, $\mathfrak{h}_3^{\mathbb{C}}$ and $\mathfrak{n}_0^{\mathbb{Q}} \otimes \mathbb{R}$ is respectively parametrized by

$$\{\mathfrak{n}_k^{\mathbb{Q}}: k > 0 \text{ is square free}\}, \qquad \{\mathfrak{n}_{-k}^{\mathbb{Q}}: k > 0 \text{ is square free}\}, \qquad \{\mathfrak{n}_0^{\mathbb{Q}}\}$$

Proof. The Lie bracket of $\mathfrak{h}_3 \oplus \mathfrak{h}_3$ is

$$X_1, X_2] = Z_1, \qquad [X_3, X_4] = Z_2,$$

and one can easily check that the rational subspace generated by the set

$$\left\{X_1+X_3, \sqrt{k}(X_1-X_3), \sqrt{k}(X_2+X_4), X_2-X_4, \sqrt{k}(Z_1+Z_2), Z_1-Z_2\right\},\$$

is a rational subalgebra of $\mathfrak{h}_3 \oplus \mathfrak{h}_3$ isomorphic to $\mathfrak{n}_k^{\mathbb{Q}}$. For $\mathfrak{h}_3^{\mathbb{C}}$, we argue in an analogous way by using $\{\sqrt{-k}X_1, X_2, X_3, \sqrt{-k}X_4, \sqrt{-k}Z_1, -kZ_2\}$.

We now describe the results in [GS] for the general case (see also [Ga]). Consider $\mathbf{n} = \mathbf{n}_1 \oplus \mathbf{n}_2$ a vector space over K such that \mathbf{n}_1 and \mathbf{n}_2 are subspaces of dimension n and 2 respectively. Every 2-step nilpotent Lie algebra of dimension n + 2 with a 2-dimensional center can be represented by a bilinear form $\mu : \mathbf{n}_1 \times \mathbf{n}_1 \longrightarrow \mathbf{n}_2$ which is non-degenerate in the following way: for any nonzero $X \in \mathbf{n}_1$ there exists $Y \in \mathbf{n}_1$ such that $\mu(X, Y) \neq 0$. If we fix basis $\{X_1, ..., X_n\}$ and $\{Z_1, Z_2\}$ of \mathbf{n}_1 and \mathbf{n}_2 respectively, then each μ has an associated Pfaffian binary form f_{μ} defined by

$$f_{\mu}(x,y) = \operatorname{Pf}(J_{xZ_1+yZ_2}^{\mu})$$

(see Definition 2.2). A central decomposition of μ is given by a decomposition of \mathfrak{n}_1 in a direct sum of subspaces $\mathfrak{n}_1 = V_1 \oplus ... \oplus V_r$ such that $\mu(V_i, V_j) = 0$ for all $i \neq j$. We say that μ is *indecomposable* when the only possible central decomposition has r = 1. Every μ has a central decomposition into indecomposables constituents and such a decomposition is unique up to an automorphism of μ ; in particular, the constituents $V_i \oplus \mathfrak{n}_2$ are unique up to isomorphism.

There is only one indecomposable μ for n odd and it can be defined by

$$J_{xZ_1+yZ_2}^{\mu} = \begin{bmatrix} & & & & & -x & -y & & 0 \\ & & & & 0 & & & \\ & 0 & & & \ddots & \ddots & \\ & & 0 & & & & \ddots & \\ \hline x & 0 & & 0 & & & \\ x & 0 & y & \ddots & & 0 & & \\ & & \ddots & x & & & & & \\ 0 & y & y & & & & & & \\ \end{bmatrix}$$

Recall that $f_{\mu} = 0$ in this case. When *n* is even the situation is much more abundant: two indecomposables μ and λ are isomorphic if and only if $f_{\mu} \simeq_K f_{\lambda}$. If

$$n = 2m$$
 and $f_{\mu}(x, y) = x^m - a_1 x^{m-1} y - \dots - a_m y^m$, then
$$J^{\mu}_{xZ_1+yZ_2} = \begin{bmatrix} 0 & -B^t \\ B & 0 \end{bmatrix},$$
where

where

$$B = \begin{bmatrix} x & y & 0 & \cdots & 0 \\ 0 & x & y & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & x & y \\ a_{m}y & a_{m-1}y & \cdots & a_{2}y & a_{1}y + x \end{bmatrix}$$

We note that here f_{μ} is always nonzero, and in order to get μ indecomposable one needs the form f_{μ} to be primitive (i.e. a power of an irreducible one). For decomposable μ and λ with respective central decompositions $\mathfrak{n}_1 = V_1 \oplus ... \oplus V_r$ and $\mathfrak{n}_1 = W_1 \oplus ... \oplus W_s$ into indecomposables constituents, we have that μ is isomorphic to λ if and only if r = s and after a suitable reordering one has that

- (i) for some $t \leq r$, dim $V_i = \dim W_i$ for all i = 1, ..., t and they are all even numbers;
- (ii) if $\mu_i = \mu|_{V_i \times V_i}$, $\lambda_i = \lambda|_{W_i \times W_i}$ then there exist $A \in GL_2(K)$ and $c_1, ..., c_t \in K^*$ such that

 $f_{\mu_i}(x,y) = c_i f_{\lambda_i}(A(x,y)) \qquad \forall \ i = 1, ..., t;$

(iii) dim V_i = dim W_i is odd for all i = t + 1, ..., r.

Concerning our search for all rational forms up to isomorphism of a given real nilpotent Lie algebra, these results say that the picture in the 2-step nilpotent with 2-dimensional center case is as follows. Let $(\mathfrak{n}^{\mathbb{Q}} = \mathfrak{n}_1 \oplus \mathfrak{n}_2, \mu)$ be one of such Lie algebras over \mathbb{Q} , and consider the corresponding Pfaffian form $f_{\mu} \in P_{2,m}(\mathbb{Q})$. The isomorphism classes of rational forms of $\mathfrak{n}^{\mathbb{Q}} \otimes \mathbb{R}$ are then parametrized by

(4)
$$\left((\mathbb{R}^* \times \mathrm{GL}_2(\mathbb{R})) . f_{\mu} \cap P_{2,m}(\mathbb{Q}) \right) / (\mathbb{Q}^* \times \mathrm{GL}_2(\mathbb{Q})).$$

In other words, the rational points of the orbit $(\mathbb{R}^* \times \operatorname{GL}_2(\mathbb{R})).f_{\mu}$ $(f_{\mu}$ viewed as an element of $P_{2,m}(\mathbb{R})$) is a $(\mathbb{Q}^* \times \operatorname{GL}_2(\mathbb{Q}))$ -invariant set and we have to consider the orbit space for this action. Such a description shows the high difficulty of the problem. Recall that we have to consider the action of $\mathbb{R}^* \times \operatorname{GL}_2(\mathbb{R})$ instead of just that of $\operatorname{GL}_2(\mathbb{R})$ only when m is even.

We now describe a duality for 2-step nilpotent Lie algebras over any field of characteristic zero introduced by J. Scheuneman [S] (see also [Ga] and [GSS, Section 8]), which assigns to each Lie algebra of type (n, k) another one of type $\left(n, \frac{n(n-1)}{2} - k\right)$. The *dual* of a Lie algebra $\mathbf{n} = \mathbf{n}_1 \oplus \mathbf{n}_2$ of type (n, k) can be defined as follows: consider the maps $\{J_Z : Z \in \mathbf{n}_2\} \subset \mathfrak{so}(n)$ corresponding to a fixed inner product $\langle \cdot, \cdot \rangle$ on \mathbf{n} (see (1)). Let $\tilde{\mathbf{n}}_2 \subset \mathfrak{so}(n)$ be the orthogonal complement of the k-dimensional subspace $\{J_Z : Z \in \mathbf{n}_2\}$ in $\mathfrak{so}(n)$ relative to the inner product $(A, B) = -\operatorname{tr} AB$. Now, we define the 2-step nilpotent Lie algebra $\tilde{\mathbf{n}} = \mathbf{n}_1 \oplus \tilde{\mathbf{n}}_2$ whose Lie bracket is determined by

$$([X,Y],Z) = \langle Z(X),Y\rangle, \qquad Z \in \tilde{\mathfrak{n}}_2.$$

In other words, the maps \tilde{J}_Z 's for this Lie algebra are the Z's themselves. Recall that dim $\tilde{\mathfrak{n}}_2 = \frac{n(n-1)}{2} - k$, and so the dual $\tilde{\mathfrak{n}}$ of \mathfrak{n} is of type $\left(n, \frac{n(n-1)}{2} - k\right)$. It

Notation	Type	Lie $brackets$
\mathfrak{h}_{2k+1}	(2k, 1)	$[X_1, X_2] = Z_1, \dots, [X_{2k-1}, X_{2k}] = Z_1$
f3	(3, 3)	$[X_1, X_2] = Z_1, [X_1, X_3] = Z_2, [X_2, X_3] = Z_3$
g	(6, 2)	$[X_1, X_2] = Z_1, [X_1, X_3] = Z_2, [X_4, X_5] = Z_1, [X_4, X_6] = Z_2$
h	(4, 4)	$[X_1, X_3] = Z_1, [X_1, X_4] = Z_2, [X_2, X_3] = Z_3, [X_2, X_4] = Z_4$
\mathfrak{l}_4	(2, 1, 1)	$[X_1, X_2] = X_3, [X_1, X_3] = X_4$

TABLE 1. Notation for some real nilpotent Lie algebras.

is proved in [S] that \mathfrak{n}_1 is isomorphic to \mathfrak{n}_2 if and only if $\tilde{\mathfrak{n}}_1$ is isomorphic to $\tilde{\mathfrak{n}}_2$, so that any classification for algebras of type (n, k) simultaneously determines the algebras of type $\left(n, \frac{n(n-1)}{2} - k\right)$.

4. Applications

In this section, we determine the set of all rational forms up to isomorphism for some 2-step 8-dimensional nilpotent Lie algebras, as an application of the results described in Sections 2 and 3. We refer to Tables 1 and 2 for a summary of the results obtained.

Let \mathfrak{g} be the 8-dimensional 2-step nilpotent Lie algebra of type (6,2) defined by

(5)
$$[X_1, X_2] = Z_1, \quad [X_1, X_3] = Z_2, \quad [X_4, X_5] = Z_1, \quad [X_4, X_6] = Z_2$$

It is easy to see that its Pfaffian form f is zero. Let $\mathfrak{g}^{\mathbb{Q}}$ be a rational form of \mathfrak{g} , for which we can assume that $\mathfrak{g}^{\mathbb{Q}} = \langle X_1, ..., X_6 \rangle_{\mathbb{Q}} \oplus \langle Z_1, Z_2 \rangle_{\mathbb{Q}}$. Since the Pfaffian form g of $\mathfrak{g}^{\mathbb{Q}}$ satisfies $g \simeq_{\mathbb{R}} f = 0$ we obtain that g = 0. It follows that $\mathfrak{g}^{\mathbb{Q}}$ can not be indecomposable, and so $\langle X_1, ..., X_6 \rangle_{\mathbb{Q}} = V_1 \oplus ... \oplus V_r$ with $[V_i, V_j] = 0$ for all $i \neq j$. Now, $\langle X_1, ..., X_6 \rangle_{\mathbb{R}} = V_1 \otimes \mathbb{R} \oplus ... \oplus V_r \otimes \mathbb{R}$ is also a central decomposition for \mathfrak{g} , proving that r = 2 and dim $V_1 = \dim V_2 = 3$ by the uniqueness of such a decomposition. But 3 is odd, and hence we obtain the following result.

Proposition 4.1. The Lie algebra \mathfrak{g} of type (6,2) given in (5) has only one rational form up to isomorphism, denoted by $\mathfrak{g}^{\mathbb{Q}}$.

Remark 4.2. Clearly, the same proof is valid if one need to find all real forms of the complex Lie algebra $\mathfrak{g}_{\mathbb{C}} = \mathfrak{g} \otimes \mathbb{C}$. Thus \mathfrak{g} is the only real form of $\mathfrak{g}_{\mathbb{C}}$ up to isomorphism.

As another application of the correspondence with binary forms given above, we now study rational forms of the real Lie algebra $\mathfrak{h}_3 \oplus \mathfrak{h}_5$ of type (6, 2). It has central decomposition $\mathfrak{n}_1 = V_1 \oplus V_2 \oplus V_3$ with dim $V_i = 2$ for all i as a real Lie algebra and its Pfaffian form is $f(x, y) = xy^2$. Let $\mu : \mathfrak{n}_1 \times \mathfrak{n}_1 \longrightarrow \mathfrak{n}_2$ be a rational form of $\mathfrak{h}_3 \oplus \mathfrak{h}_5$ with Pfaffian form f_{μ} . If μ is decomposable then $\mathfrak{n}_1 = W_1 \oplus W_2$,

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dim $W_1 = 2$, dim $W_2 = 4$; or $\mathfrak{n}_1 = W_1 \oplus W_2 \oplus W_3$, dim $W_i = 2$ for all *i*. In any case, $f_{\mu_i} \simeq_{\mathbb{Q}} x, y$ or y^2 proving that μ must be isomorphic to the canonical rational form

$$\mu_0(X_1, X_2) = Z_1, \quad \mu_0(X_3, X_4) = Z_2, \quad \mu_0(X_5, X_6) = Z_2,$$

for which $f_{\mu_0} = f$. We then assume that μ is indecomposable. We shall prove that there is only one $\operatorname{GL}_2(\mathbb{Q})$ -orbit of rational points in $\operatorname{GL}_2(\mathbb{R})$. f, and so μ will have to be isomorphic to μ_0 . There exists $A \in \operatorname{GL}_2(\mathbb{R})$ such that $f_{\mu} = A^{-1}.f$, that is,

$$f_{\mu}(x,y) = ac^{2}x^{3} + c(2ad + bc)x^{2}y + d(ad + 2bc)xy^{2} + bd^{2}y^{3}, \qquad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

Since μ is rational we have that

$$q := ac^2, \qquad r := c(2ad + bc), \qquad s := d(ad + 2bc), \qquad t := bd^2$$

are all in \mathbb{Q} . If c = 0 then q = r = 0 and $s = ad^2$, $t = bd^2$, which implies that $s \neq 0$ and hence

$$f_{\mu} = B^{-1} f$$
, for $B = \begin{bmatrix} s & t \\ 0 & 1 \end{bmatrix} \in \operatorname{GL}_2(\mathbb{Q}).$

If $c \neq 0$ then one can check by a straightforward computation that

$$\frac{d}{c} = \frac{9qst + rs^2 - 6r^2t}{6qs^2 - r^2s - 9qrt} \in \mathbb{Q}.$$

There must be a simpler formula for $\frac{d}{c}$ in terms of q, r, s, t, but unfortunately we were not able to find it. By putting $u := \frac{d}{c}$ we have that

$$f_{\mu} = B^{-1} \cdot f,$$
 for $B = \begin{bmatrix} q \ t/u^2 \\ 1 \ u \end{bmatrix} \in \operatorname{GL}_2(\mathbb{Q}).$

Recall that det $B = qu - \frac{t}{u^2} = c(ad - bc) = c \det A \neq 0$. We then obtain that in any case $f_{\mu} \simeq_{\mathbb{Q}} f$ and so μ is isomorphic to μ_0 .

Proposition 4.3. Up to isomorphism, the real Lie algebra $\mathfrak{h}_3 \oplus \mathfrak{h}_5$ of type (6,2) has only one rational form, which will be denoted by $(\mathfrak{h}_3 \oplus \mathfrak{h}_5)^{\mathbb{Q}}$.

Remark 4.4. It is easy to check that the above proof is also valid if we replace \mathbb{Q} and \mathbb{R} by \mathbb{R} and \mathbb{C} , obtaining in this way that the only real form of $(\mathfrak{h}_3 \oplus \mathfrak{h}_5)_{\mathbb{C}}$ is $\mathfrak{h}_3 \oplus \mathfrak{h}_5$.

Let \mathfrak{h} be the Lie algebra of type (4,4) which is dual to $\mathfrak{h}_3 \oplus \mathfrak{h}_3$ (of type (4,2)). The Lie bracket of $\mathfrak{h}_3 \oplus \mathfrak{h}_3$ is

$$[X_1, X_2] = Z_1, \qquad [X_3, X_4] = Z_2,$$

and hence

$$J_{Z_1} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \qquad J_{Z_2} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

The orthogonal complement $\tilde{\mathfrak{n}}_2$ of $\{J_Z : Z \in \mathfrak{n}_2\}$ is then linearly generated by

$$\begin{bmatrix} -1 & 0 \\ 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ -1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & -1 \\ 0 & 0 \end{bmatrix},$$

which determines the Lie bracket for \mathfrak{h} given by

(6)
$$[X_1, X_3] = Z_1, \quad [X_1, X_4] = Z_2, \quad [X_2, X_3] = Z_3, \quad [X_2, X_4] = Z_4.$$

Scheuneman duality allows us to find all the rational forms of \mathfrak{h} ; namely, the dual of the rational form of $\mathfrak{h}_3 \oplus \mathfrak{h}_3$, already computed in Proposition 3.2.

Proposition 4.5. For any $k \in \mathbb{Z}$ let $\mathfrak{h}_k^{\mathbb{Q}}$ be the rational Lie algebra of type (4,4) defined by

$$\begin{aligned} & [X_1, X_2] = Z_1, & [X_2, X_3] = -Z_3, \\ & [X_1, X_3] = Z_2, & [X_2, X_4] = -Z_2, \\ & [X_1, X_4] = kZ_3, & [X_3, X_4] = Z_4. \end{aligned}$$

Then the set of isomorphism classes of rational forms of the Lie algebra \mathfrak{h} defined in (6) is parametrized by

 $\{\mathfrak{h}_k^{\mathbb{Q}}: k \text{ is a square free natural number}\}.$

Proof. For the rational form $\mathfrak{n}_k^{\mathbb{Q}}$ of $\mathfrak{h}_3 \oplus \mathfrak{h}_3$ (see (3)) we have that

$$J_{Z_1} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \qquad J_{Z_2} = \begin{bmatrix} 0 & -1 \\ -k & 0 \\ 0 & k \\ 1 & 0 \end{bmatrix}.$$

A basis of the orthogonal complement of $\langle J_{Z_1}, J_{Z_2} \rangle_{\mathbb{Q}}$ is then given by

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & -k \\ 1 & 0 \\ 0 & -1 \\ k & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & -1 \\ 1 & 0 \end{bmatrix},$$

which determines the Lie bracket for $\mathfrak{h}_k^{\mathbb{Q}}$. To conclude the proof, one can easily check that the rational subspace generated by

$$\left\{\sqrt{k}(X_1 - X_3), X_1 + X_3, X_2 + X_4, \sqrt{k}(X_2 - X_4), \\ 2\sqrt{k}Z_1, \sqrt{k}(Z_2 + Z_3), Z_3 - Z_2, -2\sqrt{k}Z_4\right\},\$$

is closed under the Lie bracket of \mathfrak{h} and isomorphic to $\mathfrak{h}_k^{\mathbb{Q}}$.

An alternative proof of the non-isomorphism between the $\mathfrak{h}_k^{\mathbb{Q}}$'s without using Scheuneman duality may be given as follows: from the form of $J_{Z_1}, ..., J_{Z_4}$ for $\mathfrak{h}_k^{\mathbb{Q}}$ in the above proof it follows that

$$J_{xZ_1+yZ_2+zZ_3+wZ_4} = \begin{bmatrix} 0 & -x & -y & -kz \\ x & 0 & z & y \\ y & -z & 0 & -w \\ kz & -y & w & 0 \end{bmatrix},$$

and so the Pfaffian form of $\mathfrak{h}_k^{\mathbb{Q}}$ is given by $f_k(x, y, z, w) = xw + y^2 - kz^2$. Now, if $\mathfrak{h}_k^{\mathbb{Q}}$ is isomorphic to $\mathfrak{h}_{k'}^{\mathbb{Q}}$ then $f_k \simeq_{\mathbb{Q}} f_{k'}$ (see Proposition 2.4), which implies that $k = q^2k'$ for some $q \in \mathbb{Q}^*$ by applying Proposition 2.5 (recall that $Hf_k = 4k$). Thus k = k' since they are square free.

5. A 3-STEP NILPOTENT CASE

We compute in this section the rational forms of $l_4 \oplus l_4$, where l_4 is the 4dimensional real Lie algebra with Lie bracket

$$[Y_1, Y_2] = Y_3, \qquad [Y_1, Y_3] = Y_4.$$

Notice that $l_4 \oplus l_4$ is 3-step nilpotent, and therefore Pfaffian forms and duality can not be used as tools to distinguish or classify rational forms. For each

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Real Lie algebra	Type	Rational forms	Reference
$\mathfrak{h}_3\oplus\mathfrak{h}_3$	(4, 2)	$\mathfrak{n}_k^{\mathbb{Q}},\;k\geq 1$	Prop. 3.2
fз	(3, 3)	$\mathfrak{f}_3^\mathbb{Q}$	
g	(6, 2)	$\mathfrak{g}^{\mathbb{Q}}$	Prop. 4.1
$\mathfrak{h}_3 \oplus \mathfrak{h}_5$	(6, 2)	$(\mathfrak{h}_3\oplus\mathfrak{h}_5)^\mathbb{Q}$	Prop. 4.3
h	(4, 4)	$\mathfrak{h}_k^{\mathbb{Q}},\;k\geq 1$	Prop. 4.5
$\mathfrak{l}_4\oplus\mathfrak{l}_4$	(4, 2, 2)	$\mathfrak{l}_k^{\mathbb{Q}},\;k\geq 1$	Prop. 5.1

TABLE 2. Set of rational forms up to isomorphism for some real nilpotent Lie algebras. In all cases k runs over all square-free natural numbers.

 $k \in \mathbb{Z}$, consider the 8-dimensional rational nilpotent Lie algebra $\mathfrak{l}_{k}^{\mathbb{Q}}$ with basis $\{X_{1}, X_{2}, X_{3}, X_{4}, Z_{1}, Z_{2}, Z_{3}, Z_{4}\}$ and Lie bracket defined by

(7)
$$\begin{bmatrix} X_1, X_3 \end{bmatrix} = Z_1, \qquad \begin{bmatrix} X_2, X_3 \end{bmatrix} = Z_2, \\ \begin{bmatrix} X_1, X_4 \end{bmatrix} = Z_2, \qquad \begin{bmatrix} X_2, X_4 \end{bmatrix} = kZ_1, \\ \begin{bmatrix} X_1, Z_1 \end{bmatrix} = Z_3, \qquad \begin{bmatrix} X_2, Z_2 \end{bmatrix} = kZ_3, \\ \begin{bmatrix} X_1, Z_2 \end{bmatrix} = Z_4, \qquad \begin{bmatrix} X_2, Z_1 \end{bmatrix} = Z_4.$$

Proposition 5.1. Let $\{X_1, X_2, X_3, X_4, Z_1, Z_2, Z_3, Z_4\}$ be a basis of the Lie algebra $\mathfrak{l}_4 \oplus \mathfrak{l}_4$ of type (4, 2, 2) with structure coefficients

$$[X_1, X_3] = Z_1, \qquad [X_2, X_4] = Z_2 [X_1, Z_1] = Z_3, \qquad [X_2, Z_2] = Z_4.$$

For each $k \in \mathbb{N}$ the rational subspace generated by the set

$$\left\{ X_1 + X_2, \sqrt{k}(X_1 - X_2), X_3 + X_4, \sqrt{k}(X_3 - X_4), \\ Z_1 + Z_2, \sqrt{k}(Z_1 - Z_2), Z_3 + Z_4, \sqrt{k}(Z_3 - Z_4) \right\}$$

is a rational form of $l_4 \oplus l_4$ isomorphic to the Lie algebra $l_k^{\mathbb{Q}}$ defined in (7). Moreover, the set

 $\{\mathfrak{l}_k^{\mathbb{Q}}: k \text{ is a square-free natural number}\}$

parametrizes the set all the rational forms of $\mathfrak{l}_4 \oplus \mathfrak{l}_4$ up to isomorphism.

Proof. It is easy to see that the Lie brackets of the basis of the rational subspace coincides with the one of $\mathfrak{l}_k^{\mathbb{Q}}$ by renaming the basis as $\{X_1, ..., Z_4\}$ with the same order. In particular, such a subspace is a rational form of $\mathfrak{l}_4 \oplus \mathfrak{l}_4$. If $k' = q^2 k$ then one can easily check that $A : \mathfrak{l}_{k'}^{\mathbb{Q}} \longrightarrow \mathfrak{l}_k^{\mathbb{Q}}$ given by the diagonal matrix with entries (1, q, 1, q, 1, q, 1, q) is an isomorphism of Lie algebras.

Conversely, assume that $A : \mathfrak{l}_{k}^{\mathbb{Q}} \longrightarrow \mathfrak{l}_{k'}^{\mathbb{Q}}$ is an isomorphism. We will show that $k' = q^{2}k$ for some $q \in \mathbb{Q}^{*}$. Let $\{J'_{Z}\}, \{J_{Z}\}$ be the maps defined at the beginning of this section corresponding to $\mathfrak{l}_{k'}^{\mathbb{Q}}$ and $\mathfrak{l}_{k}^{\mathbb{Q}}$, respectively. If $Z = xZ_{1} + yZ_{2} + zZ_{3} + wZ_{4}$ we have that

$$J_{Z} = \begin{bmatrix} 0 & 0 & -x & -y & -z & -w & 0 & 0 \\ 0 & 0 & -y & -kx & -w & -kz & 0 & 0 \\ x & y & 0 & & \cdots & & 0 \\ y & kx & & & & & \\ z & w & \vdots & & & & \vdots & \vdots \\ w & kz & & & & & \\ 0 & 0 & & & & & & & 0 \end{bmatrix}$$

and J'_Z is obtained just by replacing k with k'. It follows from (2) that $A^t J'_Z A = J_{A^tZ}$ for all $Z \in \langle Z_3, Z_4 \rangle_{\mathbb{Q}}$, and since this subspace is A-invariant we get that the subspace

$$\bigcap_{Z \in \langle Z_3, Z_4 \rangle_{\mathbb{Q}}} \operatorname{Ker} J_Z = \bigcap_{Z \in \langle Z_3, Z_4 \rangle_{\mathbb{Q}}} \operatorname{Ker} J'_Z = \langle X_3, X_4, Z_3, Z_4 \rangle_{\mathbb{Q}}$$

is also A-invariant. Thus A has the form

(8)
$$A = \begin{bmatrix} A_1 & 0 & 0 & 0 \\ \star & A_2 & 0 & 0 \\ \star & 0 & A_3 & 0 \\ \star & \star & \star & A_4. \end{bmatrix}$$

(recall that $C^1(\mathfrak{l}^{\mathbb{Q}}_k) = C^1(\mathfrak{l}^{\mathbb{Q}}_{k'}) = \langle Z_1, Z_2, Z_3, Z_4 \rangle_{\mathbb{Q}}$ and $C^2(\mathfrak{l}^{\mathbb{Q}}_k) = C^2(\mathfrak{l}^{\mathbb{Q}}_{k'}) = \langle Z_3, Z_4 \rangle_{\mathbb{Q}}$ are always *A*-invariant), and now it is easy to prove that

$$A_3^t \begin{bmatrix} z & w \\ w & k'z \end{bmatrix} A_1 = \begin{bmatrix} az+bw & cz+dw \\ cz+dw & k'(az+bw) \end{bmatrix}, \text{ where } A_4^t = \begin{bmatrix} a & bw \\ c & d \end{bmatrix}.$$

We compute the determinant of both sides getting

$$qf'(z,w) = f(A_4^t(z,w)), \qquad \forall (z,w) \in \mathbb{Q}^2,$$

where $q = \det A_3 A_1 \in \mathbb{Q}^*$ and $f(z, w) = kz^2 - w^2$, $f'(z, w) = k'z^2 - w^2$. By Proposition 2.5 we have that

$$4k' = q^{-2} (\det A_4)^2 4k,$$

and so k = k' as long as they are square free numbers, as we wanted to show.

To conclude the proof, it remains to show that these are all the rational forms up to isomorphism. Let $\mathfrak{n}^{\mathbb{Q}}$ be a rational form of $\mathfrak{l}_4 \oplus \mathfrak{l}_4$. Since $\mathfrak{n}^{\mathbb{Q}}/[\mathfrak{n}^{\mathbb{Q}}, [\mathfrak{n}^{\mathbb{Q}}, \mathfrak{n}^{\mathbb{Q}}]]$ is of type (4, 2), we can use the classification of rational Lie algebras of this type given in (3) to get linearly independent vectors $X_1, ..., Z_2$ such that

(9)
$$[X_1, X_3] = Z_1, \quad [X_1, X_4] = Z_2, \quad [X_2, X_3] = Z_2, \quad [X_2, X_4] = kZ_1$$

where k is a square free integer number. Jacobi condition is equivalent to

$$[X_1, Z_2] = [X_2, Z_1], \qquad [X_3, Z_2] = [X_4, Z_1],$$
(10)

 $k[X_1, Z_1] = [X_2, Z_2], \qquad k[X_3, Z_1] = [X_4, Z_2].$

We will consider the following two cases separately:

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- (I) $Z_3 := [X_1, Z_1]$ and $Z_4 := [X_1, Z_2]$ are linearly independent,
- (II) $[X_1, Z_1], [X_1, Z_2] \in \mathbb{Q}Z_3$ for some nonzero $Z_3 \in \mathfrak{n}^{\mathbb{Q}}$.

In both cases we will make use of the following isomorphism invariant for real 3-step nilpotent Lie algebras:

$$U(\mathfrak{n}) := \{ X \in \mathfrak{n} / [\mathfrak{n}, [\mathfrak{n}, \mathfrak{n}]] : \dim \operatorname{Im}(\operatorname{ad} X) = 1 \} \cup \{ 0 \}.$$

Clearly, if $A : \mathfrak{n} \longrightarrow \mathfrak{n}'$ is an isomorphism then $AU(\mathfrak{n}) = U(\mathfrak{n}')$. Under the presentation of $\mathfrak{l}_4 \oplus \mathfrak{l}_4$ given in the statement of the theorem, it is easy to see that

(11)
$$U(\mathfrak{l}_4 \oplus \mathfrak{l}_4) = \langle X_3, Z_1 \rangle_{\mathbb{R}} \cup \langle X_4, Z_3 \rangle_{\mathbb{R}}.$$

In case (I), it follows from (10) that we also have

$$[X_2, Z_1] = Z_4, \qquad [X_2, Z_2] = kZ_3.$$

Therefore, in order to get that $\mathfrak{n}^{\mathbb{Q}}$ is isomorphic to $\mathfrak{l}_{k}^{\mathbb{Q}}$ (see (7)), it is enough to show that the vectors in $\langle Z_{3}, Z_{4} \rangle_{\mathbb{R}}$ given by

$$Z := k[X_3, Z_1] = [X_4, Z_2], \qquad Z' := [X_3, Z_2] = [X_4, Z_1]$$

are both zero (see (10)). Let us compute the cone $U(\mathfrak{n})$ for $\mathfrak{n} = \mathfrak{n}^{\mathbb{Q}} \otimes \mathbb{R}$. Recall that $U(\mathfrak{n})$ has to be the union of two disjoint planes as $\mathfrak{n} \simeq \mathfrak{l}_4 \oplus \mathfrak{l}_4$ (see (11)). If $X = aX_1 + bX_2 + cX_3 + dX_4 + eZ_1 + fZ_2$ then

$$\begin{aligned} X_1, X] &= cZ_1 + dZ_2 + eZ_3 + fZ_4, \\ X_2, X] &= dkZ_1 + cZ_2 + fkZ_3 + eZ_4, \\ X_3, X] &= -aZ_1 - bZ_2 + \frac{e}{k}Z + fZ', \\ X_4, X] &= -bkZ_1 - aZ_2 + fZ + eZ', \\ Z_1, X] &= -aZ_3 - bZ_4 - \frac{c}{k}Z - dZ', \\ Z_2, X] &= -bkZ_3 - aZ_4 - dZ - cZ'. \end{aligned}$$

Assume that $\operatorname{Im}(\operatorname{ad} X) = \mathbb{R}X_0, X_0 \neq 0$. If $k \leq 0$ then it follows easily from $[X_1, X] = \lambda[X_2, X]$ and $[X_3, X] = \mu[X_4, X]$ for some $\lambda, \mu \in \mathbb{R}$ that a = b = c = d = e = f = 0, which implies that $U(\mathfrak{n}) = \{0\}$, a contradiction.

Remark 5.2. Since k has to be positive one can also get by an easy adaptation of this proof that the only real form of $(\mathfrak{l}_4 \oplus \mathfrak{l}_4)_{\mathbb{C}}$ is $\mathfrak{l}_4 \oplus \mathfrak{l}_4$.

We then have that k > 0 and $a = \pm \sqrt{k}b$, $c = \pm \sqrt{k}d$, $e = \pm \sqrt{k}f$, where c and e have the same sign. This implies that

$$X = b(\pm\sqrt{k}X_1 + X_2) + d(\pm\sqrt{k}X_3 + X_4) + f(\pm\sqrt{k}Z_1 + Z_2)$$

and

$$\begin{split} & [X_1, X] = d(\pm\sqrt{k}Z_1 + Z_2) + f(\pm\sqrt{k}Z_3 + Z_4), \\ & [X_2, X] = \sqrt{k}[X_1, X], \\ & [X_3, X] = -b(\pm\sqrt{k}Z_1 + Z_2) + f(\pm\frac{1}{\sqrt{k}}Z + Z'), \\ & [X_4, X] = \sqrt{k}[X_3, X], \\ & [Z_1, X] = -b(\pm\sqrt{k}Z_3 + Z_4) - d(\pm\frac{1}{\sqrt{k}}Z + Z'), \\ & [Z_2, X] = \sqrt{k}[Z_1, X]. \end{split}$$

If $b \neq 0$ then $d \neq 0$ and *a* has the same sign as *c* and *e*, and since X_0 has a nonzero component in $\langle Z_1, Z_2 \rangle_{\mathbb{R}}$ we get $[Z_1, X] = 0$, that is, $-\frac{b}{d}(\pm \sqrt{k}Z_3 + Z_4) = \pm \frac{1}{\sqrt{k}}Z + Z'$. In any case we obtain a subset of $U(\mathfrak{n})$ of the form

$$\{b(\pm\sqrt{kX_1+X_2}) + d(\pm\sqrt{kX_3+X_4}) + f(\pm\sqrt{kZ_1+Z_2}) : b, d \neq 0\}$$

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with the same sign in all the terms, which is a contradiction since $U(\mathfrak{n})$ is the union of two planes. Thus b = 0 and so

 $U(\mathfrak{n}) = \langle \sqrt{k}X_3 + X_4, \sqrt{k}Z_1 + Z_2 \rangle_{\mathbb{R}} \cup \langle -\sqrt{k}X_3 + X_4, -\sqrt{k}Z_1 + Z_2 \rangle_{\mathbb{R}}.$

This clearly implies that $\frac{1}{\sqrt{k}}Z + Z' = -\frac{1}{\sqrt{k}}Z + Z' = 0$, that is Z = Z' = 0, as was to be shown.

Concerning case (II), we can assume that

$$[X_1, Z_2] = rZ_3, \quad k[X_1, Z_1] = sZ_3, \quad [X_3, Z_2] = tZ_4, \quad k[X_3, Z_1] = uZ_4,$$

where Z_3, Z_4 are linearly independent and $(s, r), (u, t) \neq (0, 0)$. By using (10), for $X = aX_1 + bX_2 + cX_3 + dX_4 + eZ_1 + fZ_2$ we have that

$$\begin{split} & [X_1, X] = cZ_1 + dZ_2 + (\frac{e}{k}s + fr)Z_3, \\ & [X_2, X] = dkZ_1 + cZ_2 + (fs + er)Z_3, \\ & [X_3, X] = -aZ_1 - bZ_2 + (\frac{e}{k}u + ft)Z_4, \\ & [X_4, X] = -bkZ_1 - aZ_2 + (fu + et)Z_4, \\ & [Z_1, X] = -(\frac{a}{k}s + br)Z_3 - (\frac{e}{k}u + dt)Z_4, \\ & [Z_2, X] = -(\frac{b}{k}s + ar)Z_3 - (\frac{d}{k}u + ct)Z_4. \end{split}$$

If a = 0 then b = c = d = 0. We also obtain that $e^2 = kf^2$, since either

$$\left[\begin{array}{cc} \frac{e}{k} & f\\ f & e\end{array}\right] \left[\begin{array}{c} s\\ r\end{array}\right] = 0 \qquad \text{or} \qquad \left[\begin{array}{cc} \frac{e}{k} & f\\ f & e\end{array}\right] \left[\begin{array}{c} u\\ t\end{array}\right] = 0.$$

We do not get any plane in $U(\mathfrak{n})$ in this way and therefore there must be an $X \in U(\mathfrak{n})$ with $a \neq 0$, which implies that $b, c, d \neq 0$ and $a^2 = kb^2$, $c^2 = kd^2$. Thus $[Z_1, X] = [Z_2, X] = 0$ and so $\operatorname{Im}(\operatorname{ad} X) \subset \langle Z_1, Z_2 \rangle_{\mathbb{R}}$. This implies that $e^2 = kf^2$ and then the 3-dimensional subspace

$$\langle \sqrt{k}X_1 + X_2, \sqrt{k}X_3 + X_4, \sqrt{k}Z_1 + Z_2 \rangle_{\mathbb{R}} \subset U(\mathfrak{n}),$$

which is a contradiction, proving that case (II) is not possible. This concludes the proof of the proposition. $\hfill \Box$

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