# A novel diffuse interface approach to brittle fracture

Verónica I. Marconi

Grupo de Teoría de la Materia Condensada FaMAF, Universidad Nacional de Córdoba.

In collaboration with E.A Jagla and S. Shenoy

Condensed Matter Group, The Abdus Salam ICTP, Trieste, Italy.

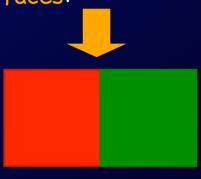
Seminario GTMC, 12 de Agosto, 2008.

### Outline

- >Introduction and Motivation.
- > Continuum model for brittle fracture.
- >Convalidation of the model in well controlled geometries.
- ➤ Some application examples.
- > Conclusions and future work.

#### Introduction

Many problems in condensed matter physics deal with sharp interfaces:



#### like:

- solidification
- dendritic growth
- · grain growth
- solid-solid transformation
- magnetic domains
- fracture

#### Solutions:

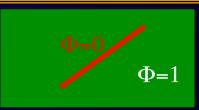
- 1) Boundary conditions at the interface. Heavy to deal....each time a new problem!
- 2) Atomistic models. Numerically heavy and how to cross to the macroscopic beh.?
- 3) Diffuse interface technique (including phase field models): regularization, additional field φ !!.

Example:

 $\begin{array}{c|c} \text{Liquid} & \text{Solid} \\ \Phi=0 & \Phi=1 \end{array}$ 

φ is an "external" degree of freedom How to deal with its dynamics???

#### Phase field models for fracture:



I. S. Aranson, V. A. Kalatsky, and V. M. Vinokur, Phys. Rev.Lett. 85, 118 (2000).

A. Karma, D. A. Kessler, and H. Levine, Phys. Rev. Lett. 87, 045501 (2001).

L. O. Eastgate, J. P. Sethna, M. Rauscher, T. Cretegny, C.S. Chen, and C. R. Myers, Phys. Rev. E 65, 036117 (2002).

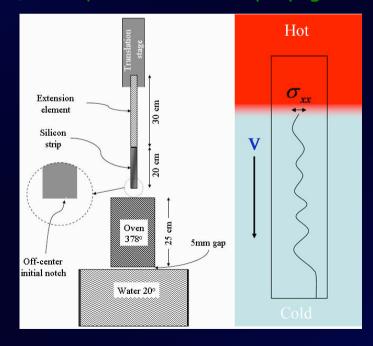
All previous have in common an external degree of freedom!

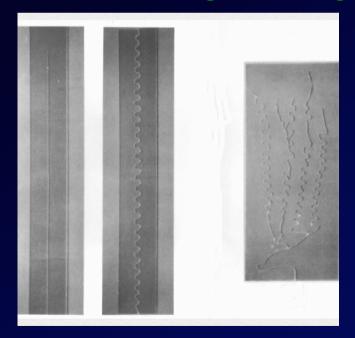
Our aim.....

"Obtain a diffuse interface approach for the propagation of cracks able to describe the properties of "isotropic materials" independently of the underlying numerical mesh without adding extra degrees of freedom."

Need to supplement macroscopic transport physics with a regularizing short scale physics in order to obtain a self-consistent theoretical framework for many problems: dendritic solidification, viscous fingering, and many examples in fracture physics as:

1)Quasi-equilibrium cracks propagation under uniaxial loading or thermal gradient





Yuse, Sano, Nature (1993)

- 2) Cracks due to shrinking:
- · changes in humidity concentration
- nonuniform temperature distribution





Picture from Salar (salty surface) Uyuni, Bolivia.

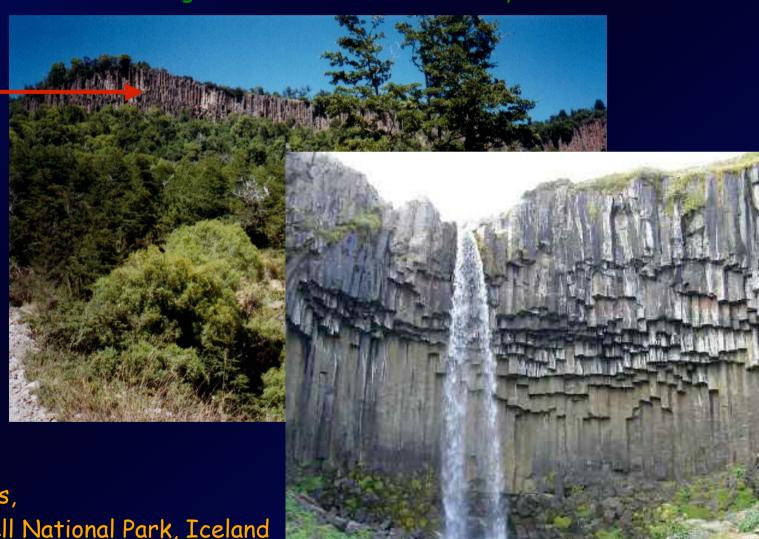
Length scale ~ meters

Tectonic plates
Length scale ~ km

3) Columnar fracturing in basaltic lava, sedimentary rocks...



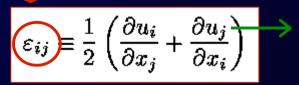
Bariloche Argentina



Svartifoss, Skaftafell National Park, Iceland

#### Model

#### Fundamental variables: "strain\_tensor components"



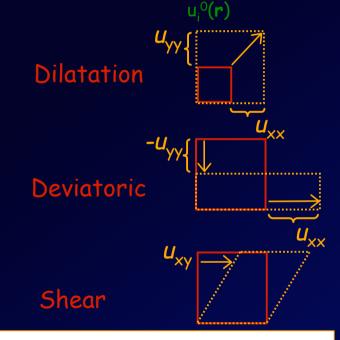
For a 2D geometry we choose:

$$e_1 = (u_{xx} + u_{yy}) / 2 = (\epsilon_{11} + \epsilon_{22}) / 2$$

$$e_2 = (u_{xx} - u_{yy}) / 2 = (\epsilon_{11} - \epsilon_{22}) / 2$$

$$e_3 = (u_{xy} + u_{yx}) = \epsilon_{12} = \epsilon_{21}$$

Displacements with respect to the unperturbated position



Attention!! Variables  $e_1$ ,  $e_2$  and  $e_3$  are not independent!

$$\nabla \times (\nabla \times \mathbf{e}) = 0$$

$$(\partial_{x}^{2} + \partial_{y}^{2}) \mathbf{e}_{1} - (\partial_{x}^{2} - \partial_{y}^{2}) \mathbf{e}_{2} - 2\partial_{x}\partial_{y} \mathbf{e}_{3} = 0$$

St Venant Condition



Textures in ferroelastic materials and martensites:

Lookman, S.R. Shenoy, Rasmussen, Saxena and Bishop, PRB (2003). S.R.Shenoy et al., PRB (1999).

#### Model

#### Local free energy density $F_{L}$ (e)?

1) For small u<sub>i</sub>(r) and small e should be...:

$$F_L^0(\varepsilon) = C_{ijkl} \varepsilon_{ij} \varepsilon_{kl} / 2 \longrightarrow$$
 "Elasticity "

Bylk and shear modulus

For isotropic material (our first aim )

$$F_L^0(\epsilon) = 2Be_1^2 + 2\mu (e_2^2 + e_3^2)$$

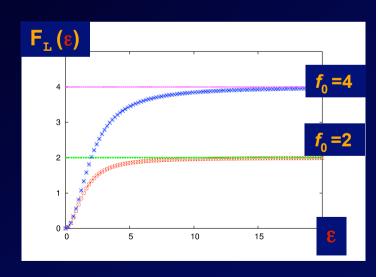
• Two crucial ingredients:

Rotational Invariance

2) How to account for fracture at large strains?

$$F_L(\varepsilon) = \frac{\mathbf{g} \, F_L^0(\varepsilon)}{[1 + F_L^0(\varepsilon)/f_0]}$$

 $g(r_{ij}) \sim 1 \rightarrow \text{Random inhomogeneities}$ 



Lim  $F_L(\varepsilon) = f_0$  (related with the crack energy)

#### Model

B) How to avoid influence from the numerical mesh? "REGULARIZATION"

$$F_{\nabla}(\varepsilon) = \sum_{i=1,2,3} \alpha_i (\nabla e_i)^2$$

$$F_{\nabla}(\varepsilon) = \sum_{i=1,2,3} \alpha_i (\nabla e_i)^2 s(e_i)$$

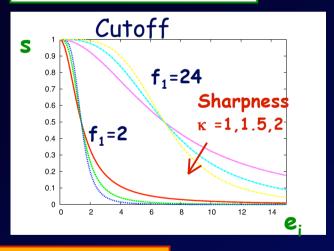
Smooth interfaces, 'a way to soften variables'

choosing

$$\alpha_2 = \alpha_3$$

(rot. invariance)

 $s(e_i)=(1+(F_L^0/f_1)^K)^{-1}$ 



Finally ... the full free energy density is defined:

Like a G.Landau free energy: with order parameter, own elastic deformations

#### Model: equations of motion

Including a kinetic term, T~p(du/dt)2/2 the eqs of motion in Fourier space,

where E<sub>i</sub> are Fourier transforms of e<sub>i</sub>:

Inertial term

Potential Force

Dissipation St.

Constraint: St. Venant

$$\frac{4\rho}{k_x^2 k_y^2} (k^2 \ddot{E}_1 + (k_x^2 - k_y^2) \ddot{E}_2) = -\frac{\delta F}{\delta E_1^*} + A_1 \dot{E}_1 + k^2 \Lambda 
\frac{4\rho}{k_x^2 k_y^2} ((k_x^2 - k_y^2) \ddot{E}_1 + k^2 \ddot{E}_2) = -\frac{\delta F}{\delta E_2^*} - A_2 \dot{E}_2 + (k_y^2 - k_x^2) \Lambda 
0 = -\frac{\delta F}{\delta E_3^*} - A_3 \dot{E}_3 - 2k_x k_y \Lambda$$

Molecular Dynamics simulations:

 $A_{i}$  phen. damping cte

Lagrange mult.

-Overdamped regime

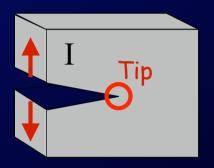
- -Periodic boundary conditions
- -Square and rectangular mesh
- -System sizes: 128x128, 512x512, 768x768, 768x256...

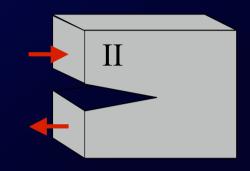
St. Venant condition in FS:

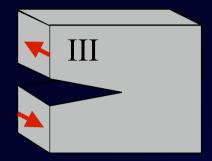
$$(k_x^2+k_y^2)E_1 - (k_x^2-k_y^2)E_2 - 2k_x k_y E_3 = 0$$

#### Convalidation of the model: "Griffith law"

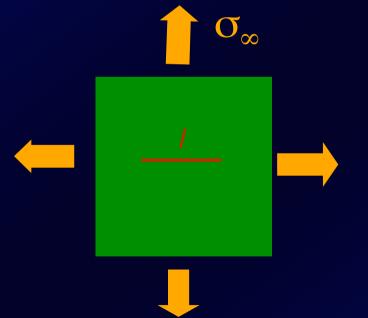
#### Loadings modes: I, II, III







Griffith law (GL)? Under uniform loading (Mode I).....



 $GL \longrightarrow For \sigma > \sigma_c$  breaks and

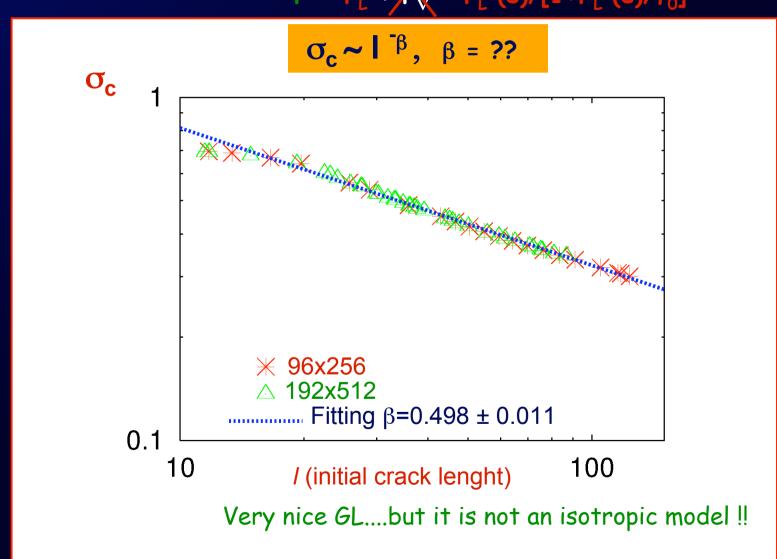
$$\sigma_c \sim 1^{-\beta} = 1^{-0.5}$$

Deduced just considering: elastic energy + crack energy

"all models for fracture should fullfill it"

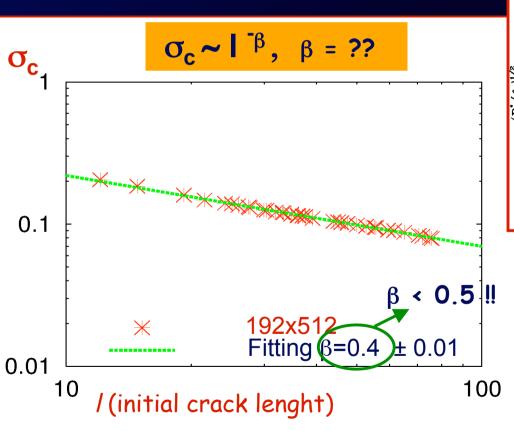
#### Griffith criterion: results

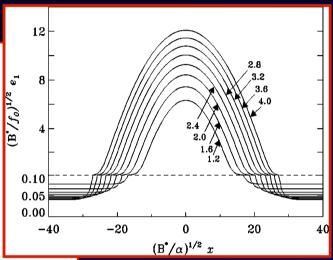
Model without regularization,  $\alpha_i = 0$   $\Rightarrow F = F_L + \sum_{k=0}^{\infty} F_k^0(e) / [1 + F_k^0(e) / f_0]$ 



#### Griffith criterion: results

Model with regularization,  $\alpha_i = 0.25$ , and  $f_1 \rightarrow \infty$  (without cutoff)  $\rightarrow F = F_L + F_{\nabla} = F_L^0(e)/[1+F_L^0(e)/f_0] + \sum_i \alpha_i (\nabla_i e_i)^2$ 



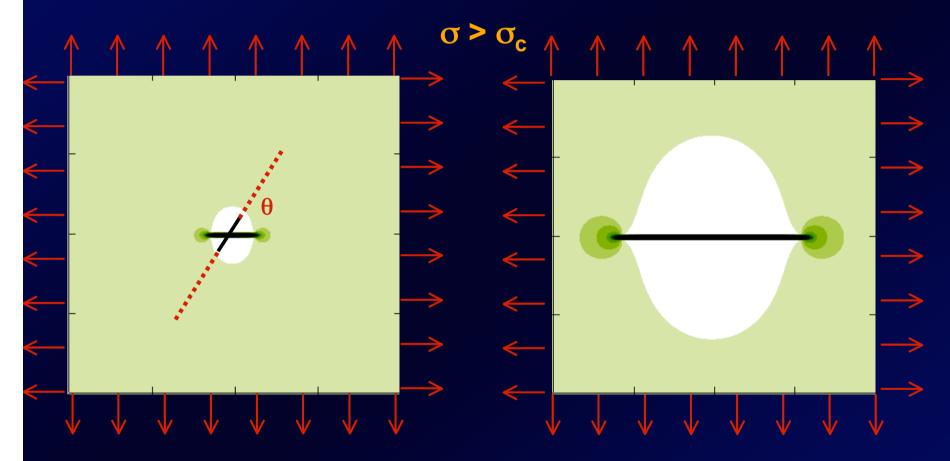


#### Griffith criterion: results

Model with regularization,  $\alpha_i$ =0.25 + finite  $f_1$  (cutoff)  $\rightarrow$  F = F<sub>L</sub> + F<sub>\nabla</sub> = F<sub>L</sub><sup>0</sup>(e)/[1+F<sub>L</sub><sup>0</sup>(e)/f<sub>0</sub>] +  $\sum \alpha_i (\nabla e_i)^2 s(e_i)$ Dilatation i=1,2,310 40  $\alpha' = 0.5$ 30 arb. units 20 10 -20 -40 40  $(B^*/\alpha)^{1/2} x$  $\Diamond \beta = 0.402 \mp 0.009, f_1 \rightarrow \infty$  $\Re$   $\beta = 0.504 \mp 0.0025, f_1 = 14.6 B$ Shear Nice scaling!! Then... a cutoff is necessary 100 -0.2 -0.3

# Results in well controlled geometries

Uniform loading (Mode I): Temote stress



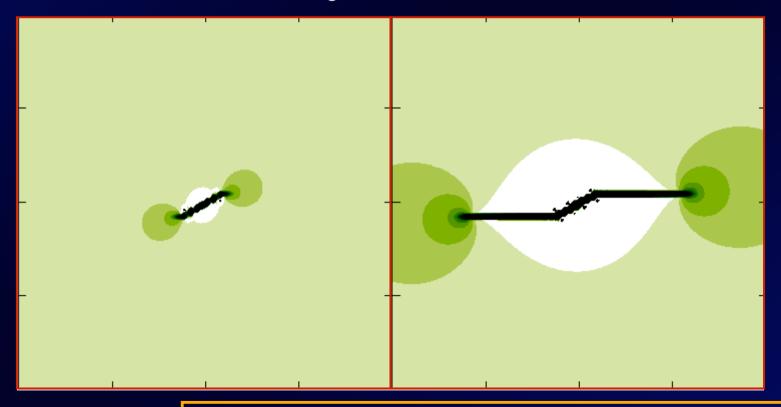
Crack propagation

# Results in well controlled geometries

Uniform loading: or remote stress

$$\sigma > \sigma_c$$

Without regularization terms!!



Typical drawback in many discrete models for fracture!!

Clear effects of underlying numerical mesh......

# Results including REGULARIZATION

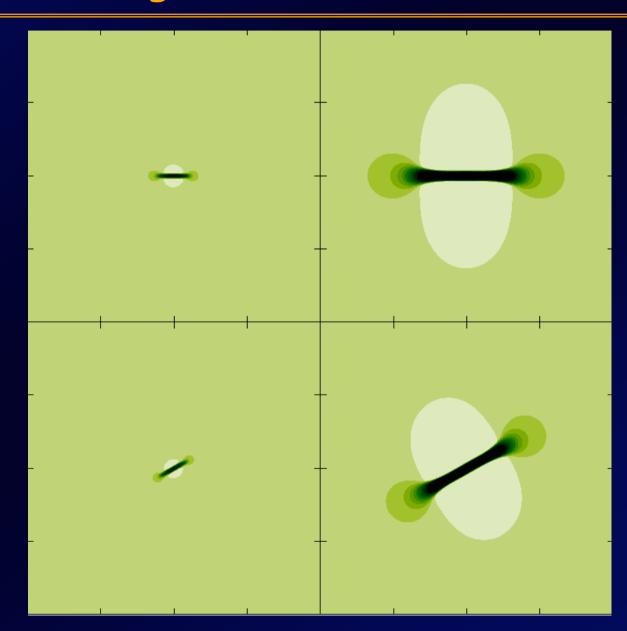
Uniform loading:

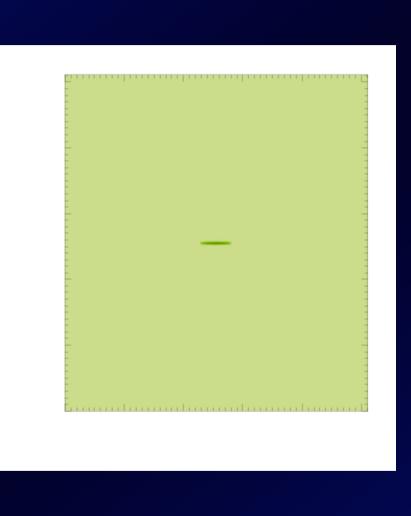
or remote stress:

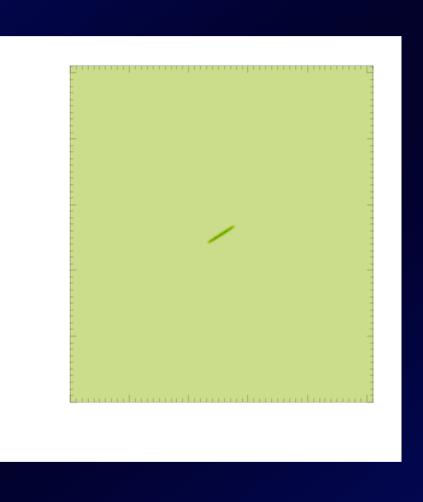
 $\sigma > \sigma_c$ 



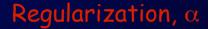


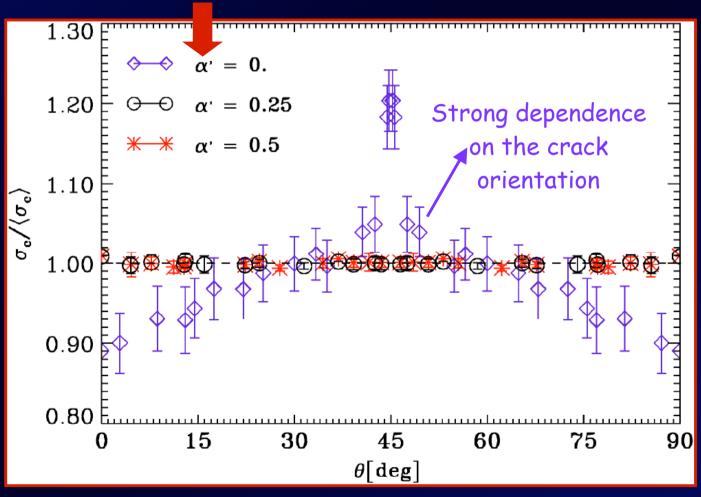






#### Critical remote stress dependence on angle

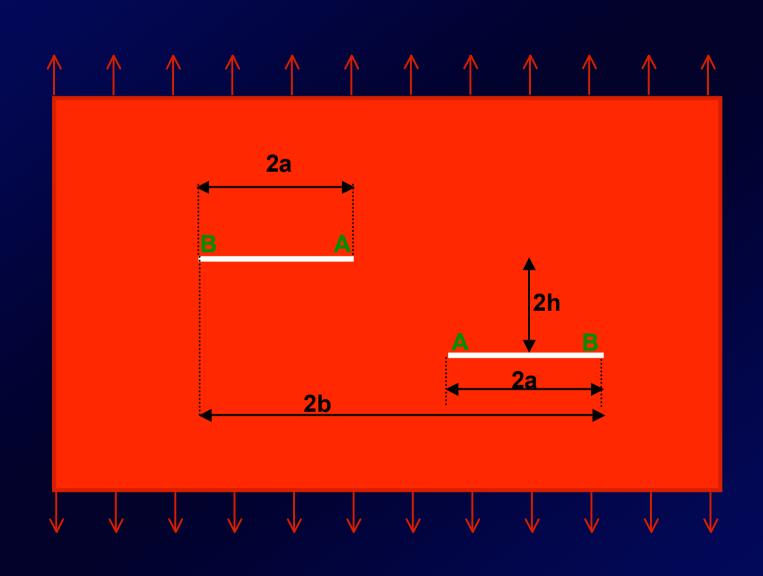




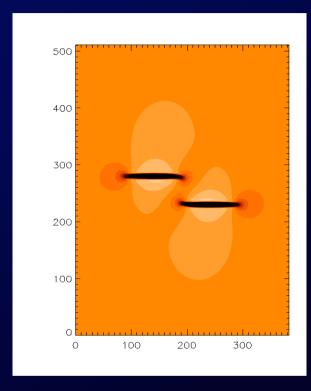
REGULARIZATION → critical stress independent of the angle!

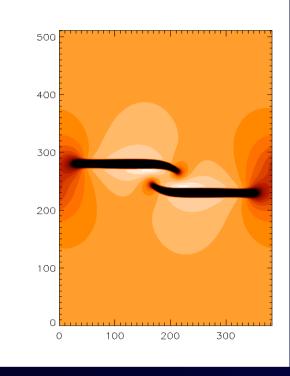
We succeed obtaining an isotropic model!!

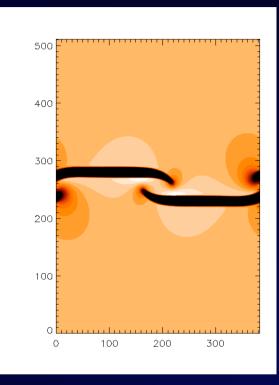
# Equal skew-parallel cracks problem



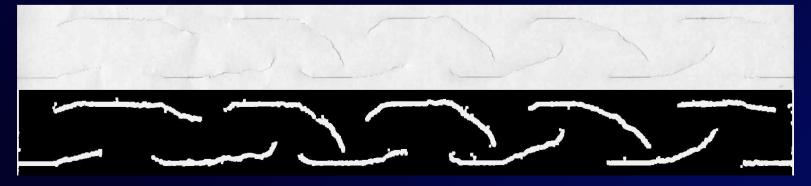
## Equal skew-parallel cracks problem



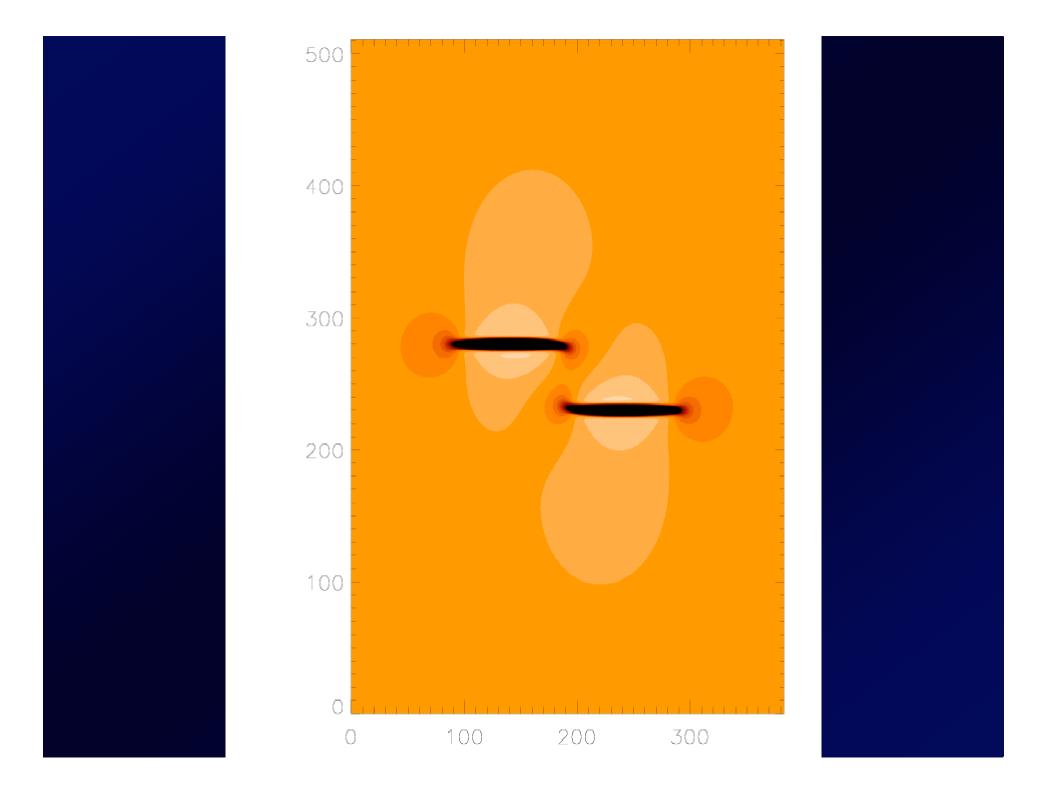




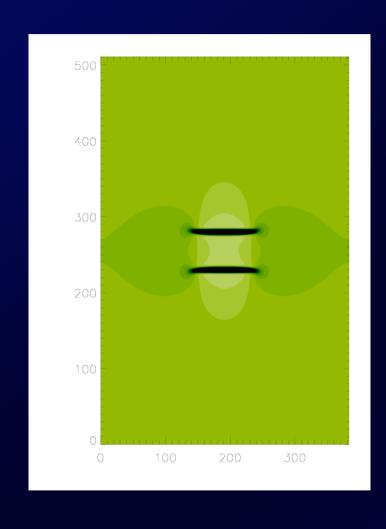
S. Ciliberto's Group experiment, Universite de Lyon, France. Cond-Mat July 2008.

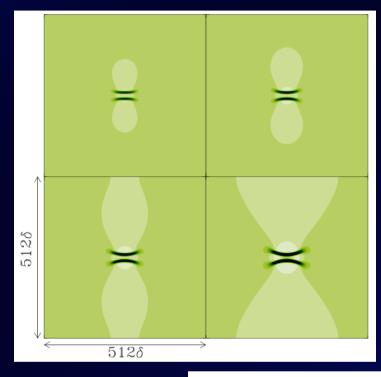


Loaded 2d brittle sample of fax paper sheet (Alrey) with a tensile Machine.

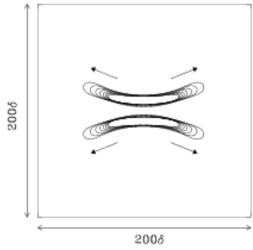


# Parallel cracks problem





Crack propagation: snapshots vs time.



#### Conclusions

#### Advantages of this model for brittle fracture:

- § Does not include additional degrees of freedom: the full set of variables are the components of the strain tensor.
- § Well defined Newtonian dynamics (plus damping).
- § Largely reduced number of uncontrolled parameters.
- § Information of 'existence and direction' of fracture in a single cell of a computational mesh.
- § Rotational invariant theory. Summarizing....

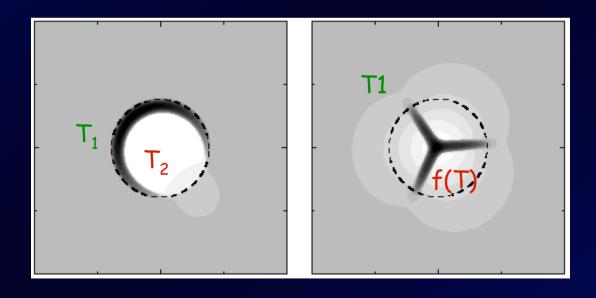
The diffuse interface approach for brittle fracture is able to reproduce well stablished facts in fracture physics and REGULARIZATION makes results insensitive to the numerical mesh used "fact not at all trivial in crack modeling".

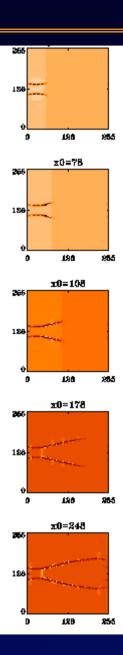
PRE 71, 036110 (2005).

#### Applications and future work

#### ⇒Quasi-static crack propagation problems:

- 1) Systems under pression.
- 2) Systems under thermal gradient.
- 3) Minimum cracks energy configuration (non uniform temperature distribution).







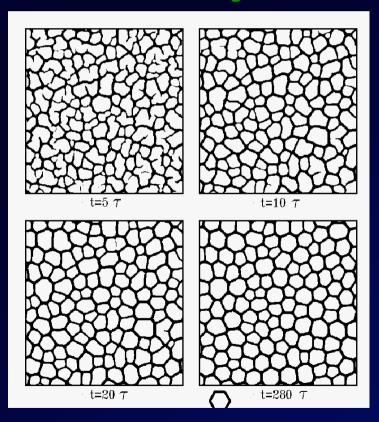
# Applications

⇒Crack maturation: Model applied to a thin layer elastically attached to a substrate + disorder

Fragmentation: first stage of evolution

# t=1 Τ

Maturation: at longer times



#### Applications and future work

⇒Dynamics of fracture: sound emission, bifurcation, cracks instabilities, .....

Preliminary simulations of the complete dynamics (underdamped or inertial) show indeed well known effects as crack bifurcation and crack oscillations.

⇒ Straightforward extension to 3D problems.

#### Acknowledgments:

-E. A. Jagla and S. R. Shenoy (ICTP, Italy) and Alain Karma (Northeastern University, Boston) for comments and useful discussions.

\$\$ Fundings from ICTP & UNESCO.

